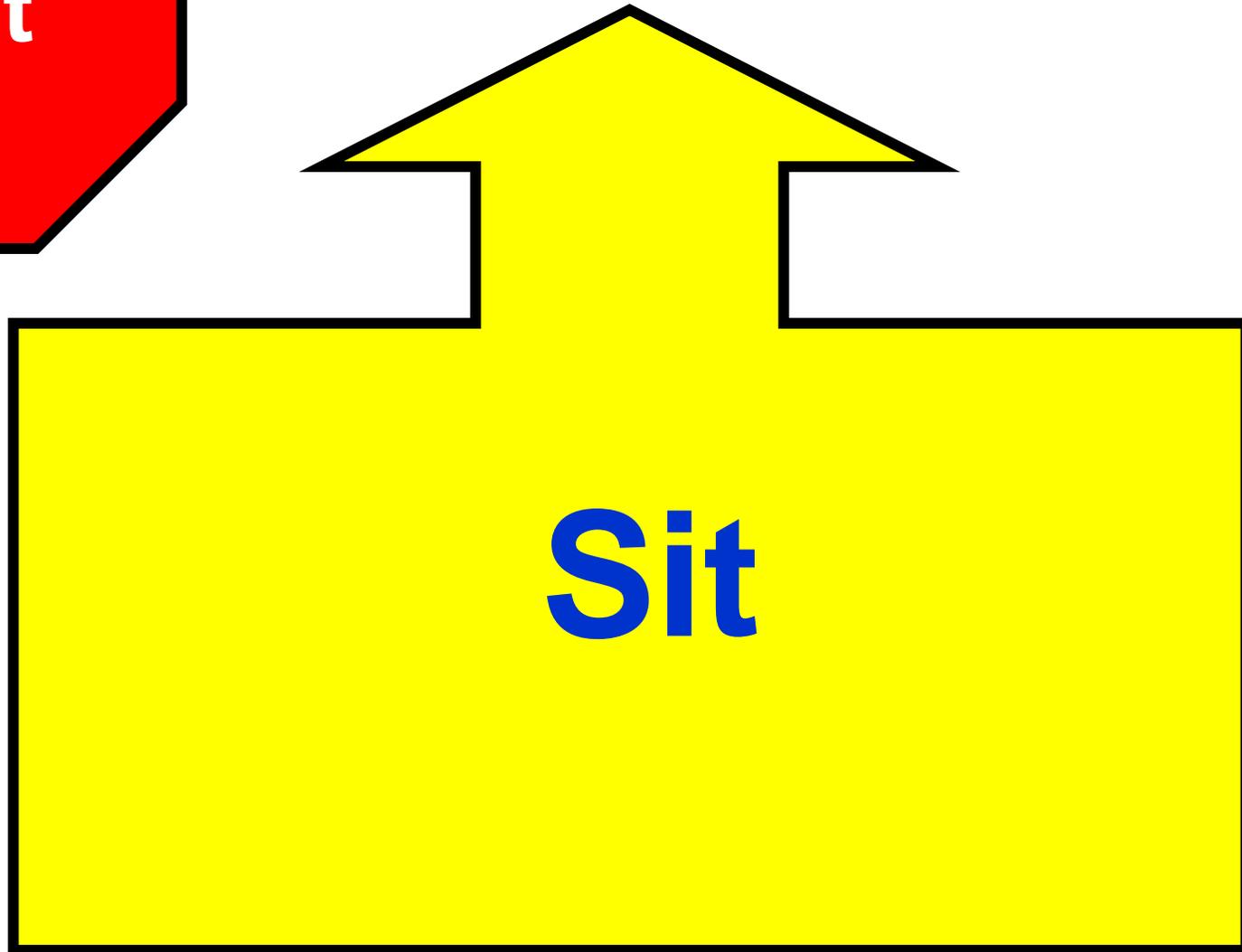
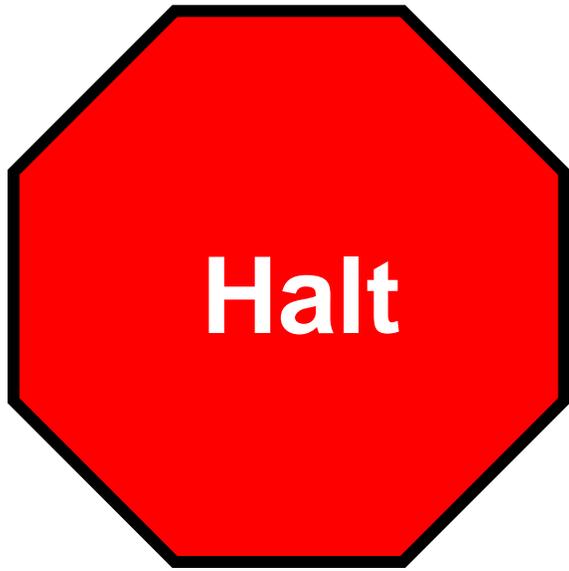
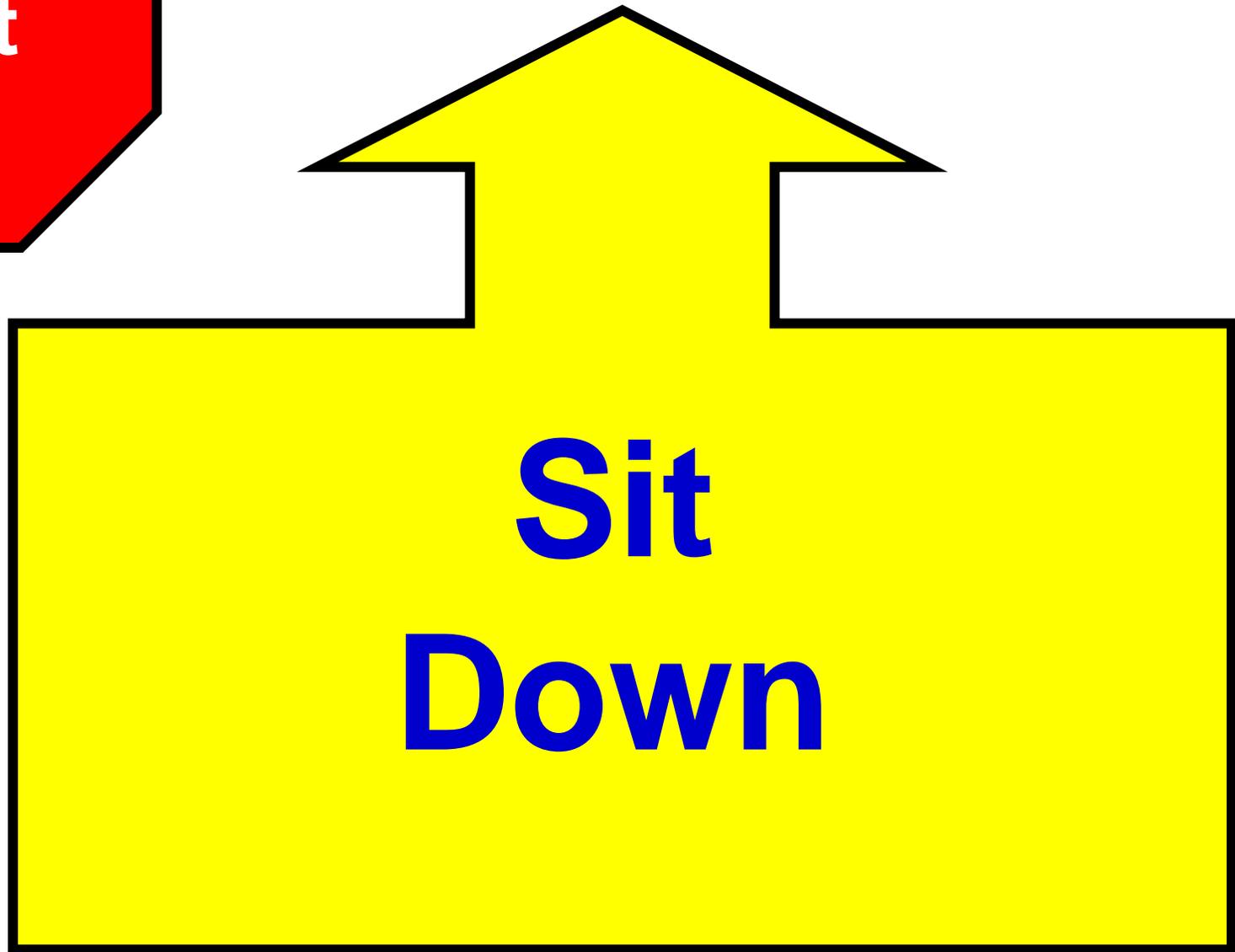
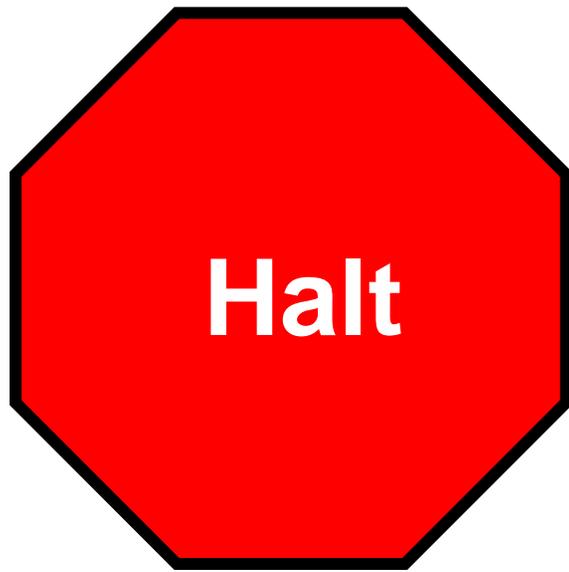


Start

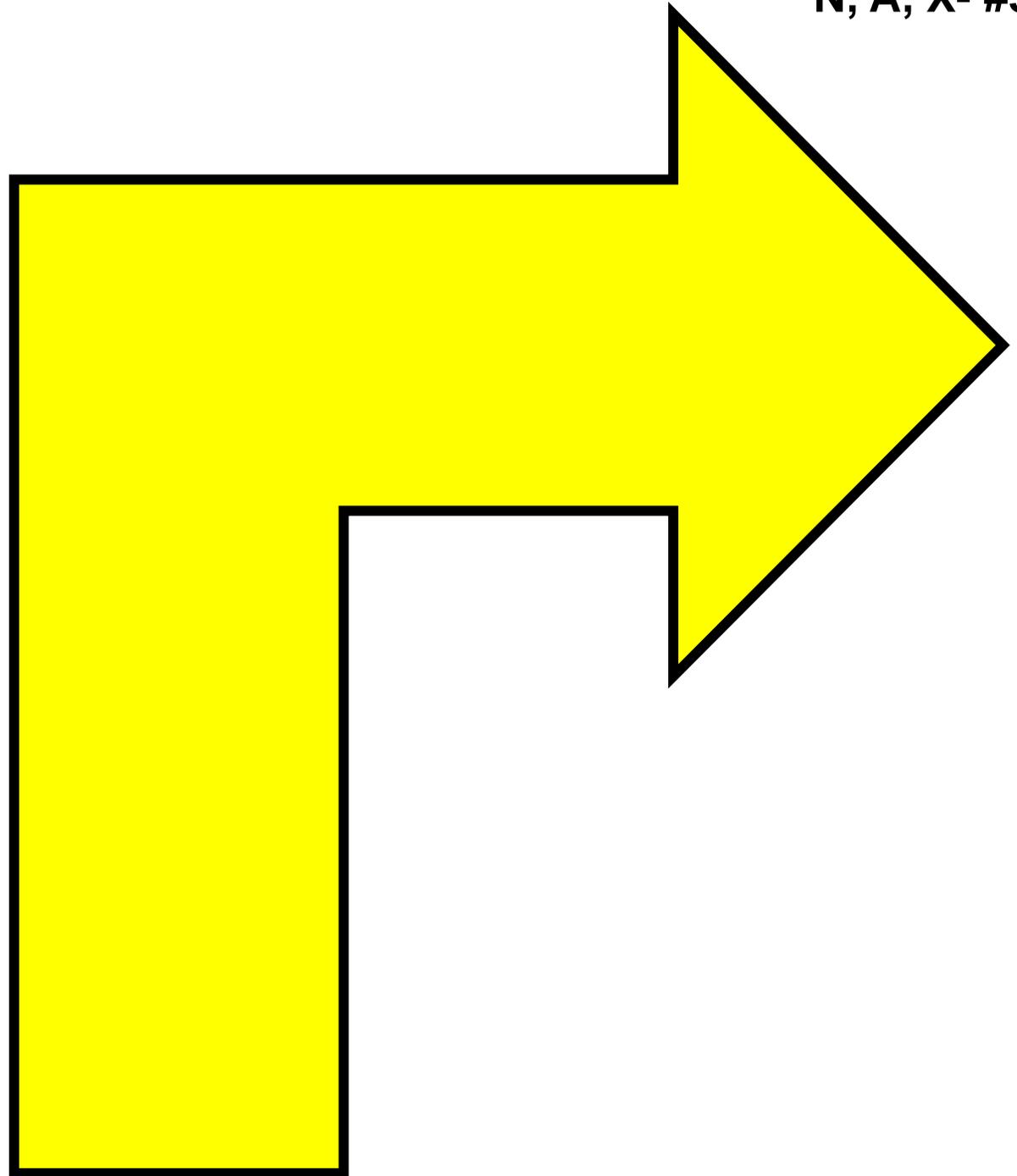






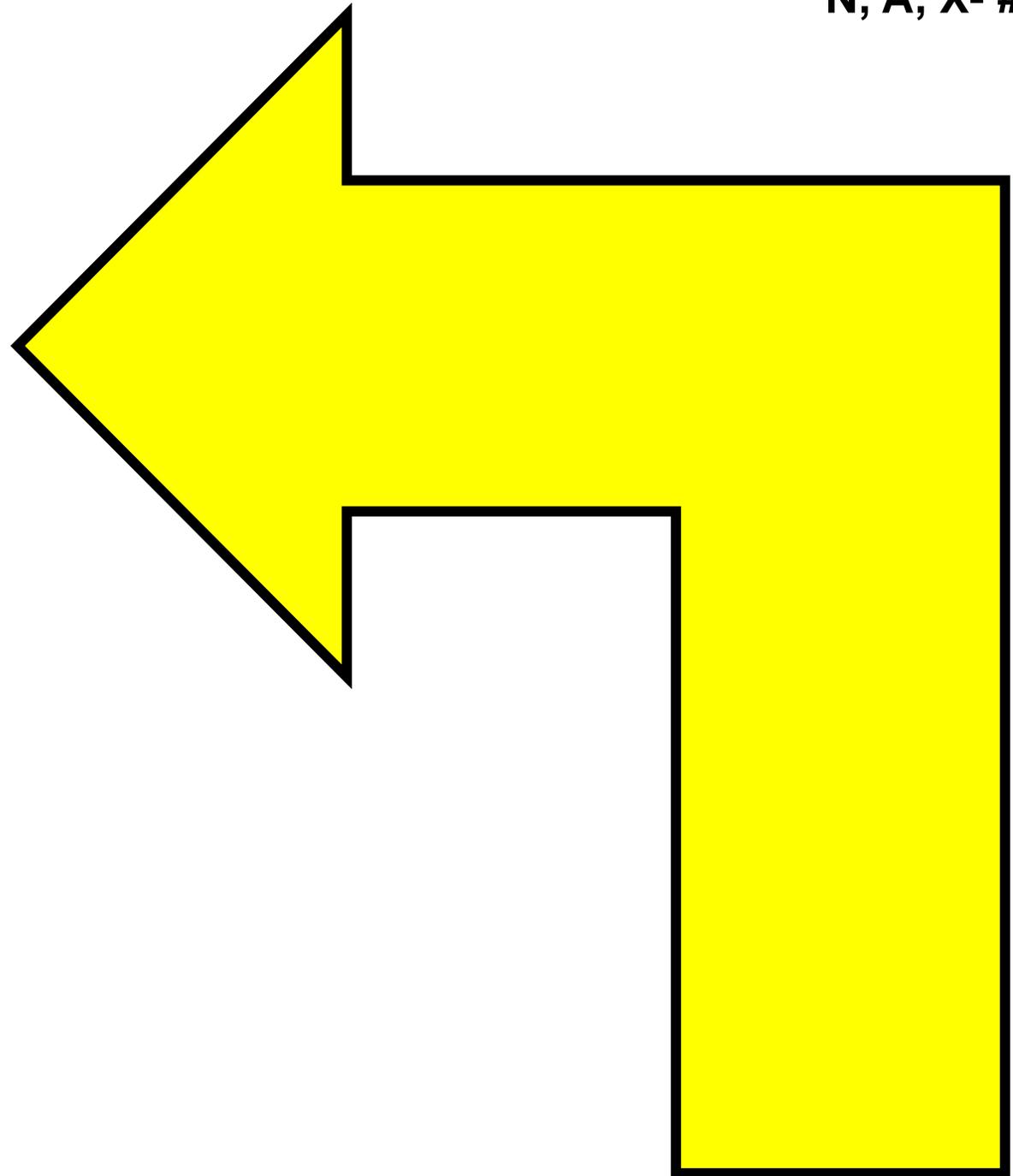


Right Turn



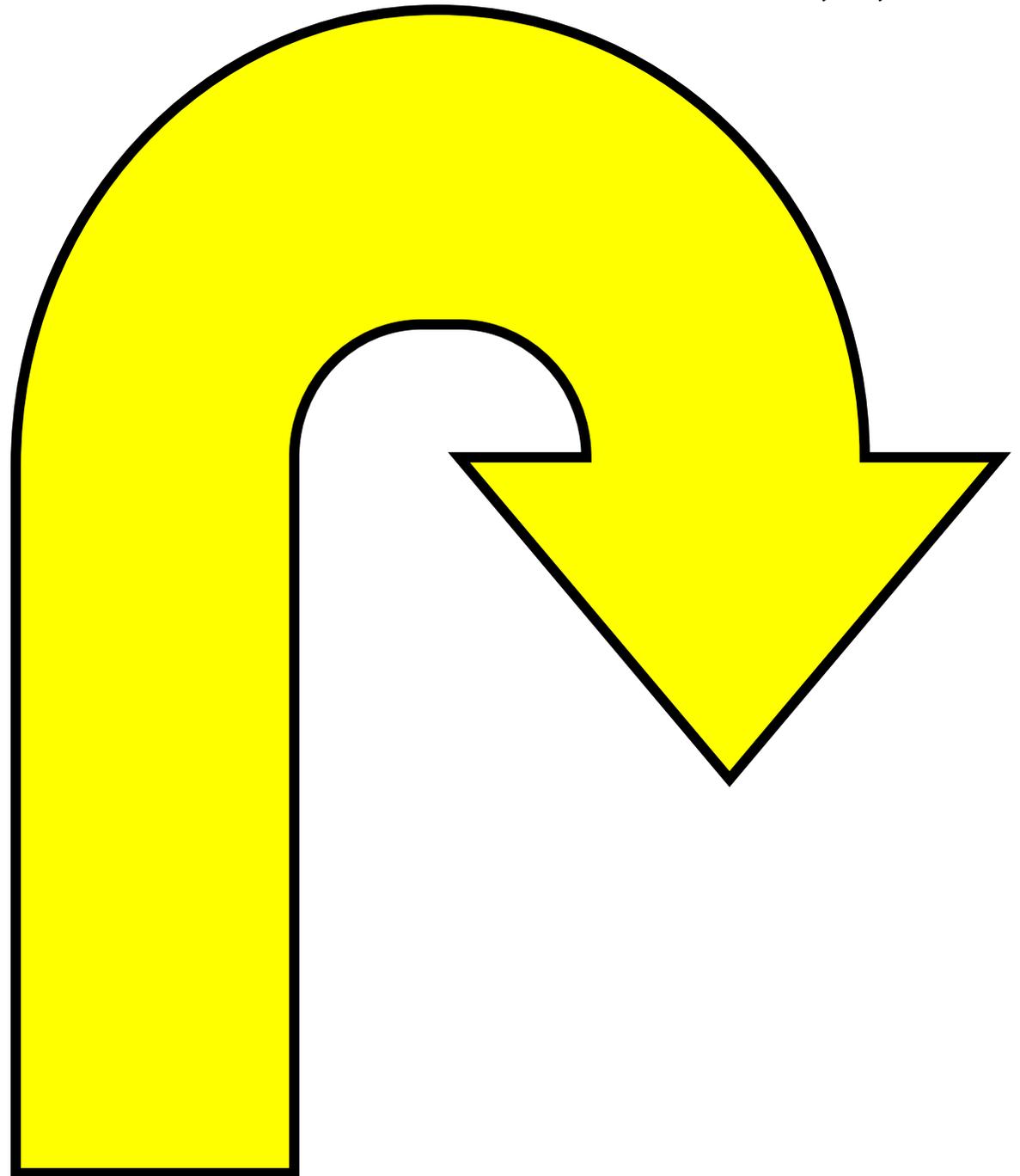


**Left
Turn**

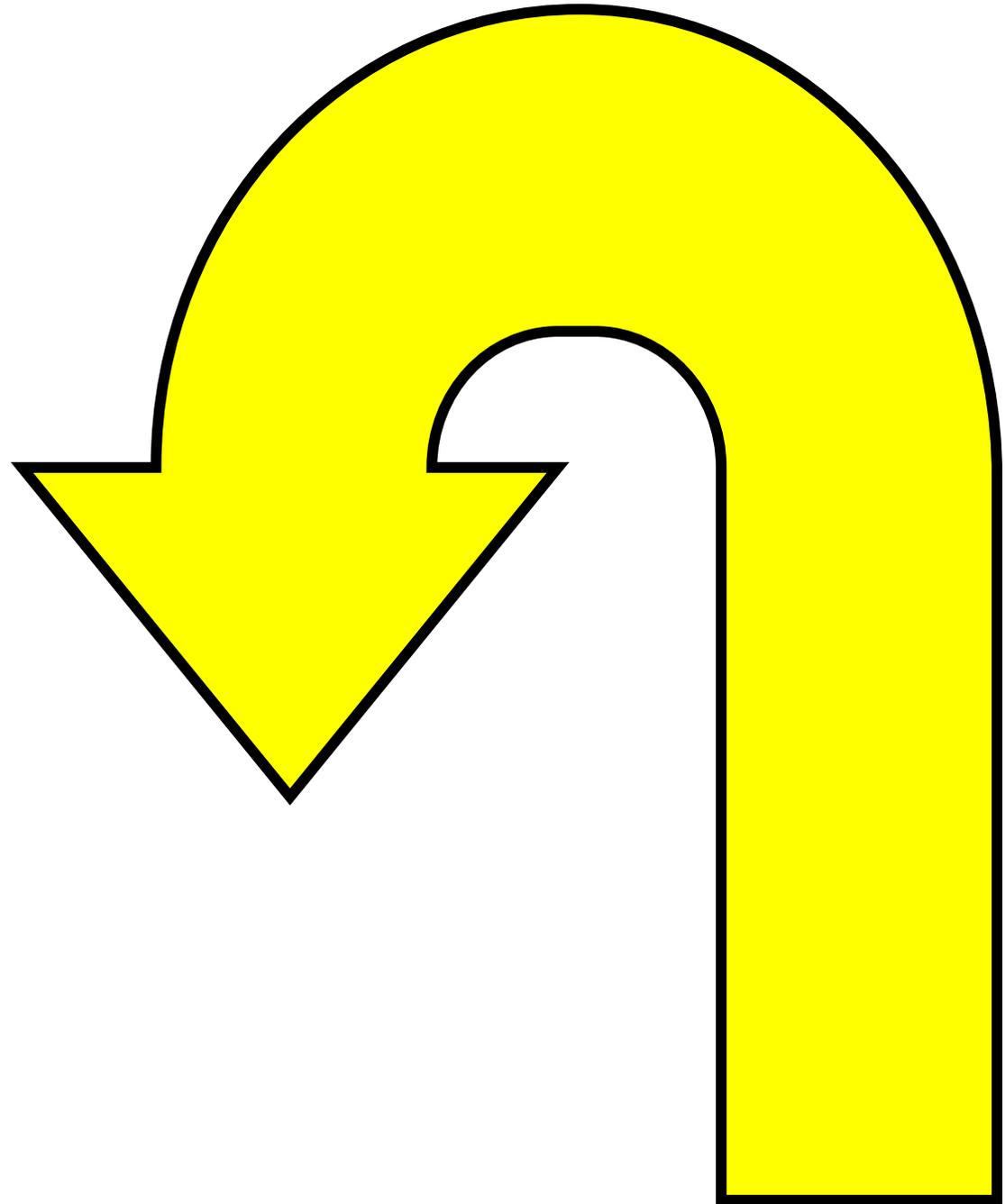




**About
Turn
Right**

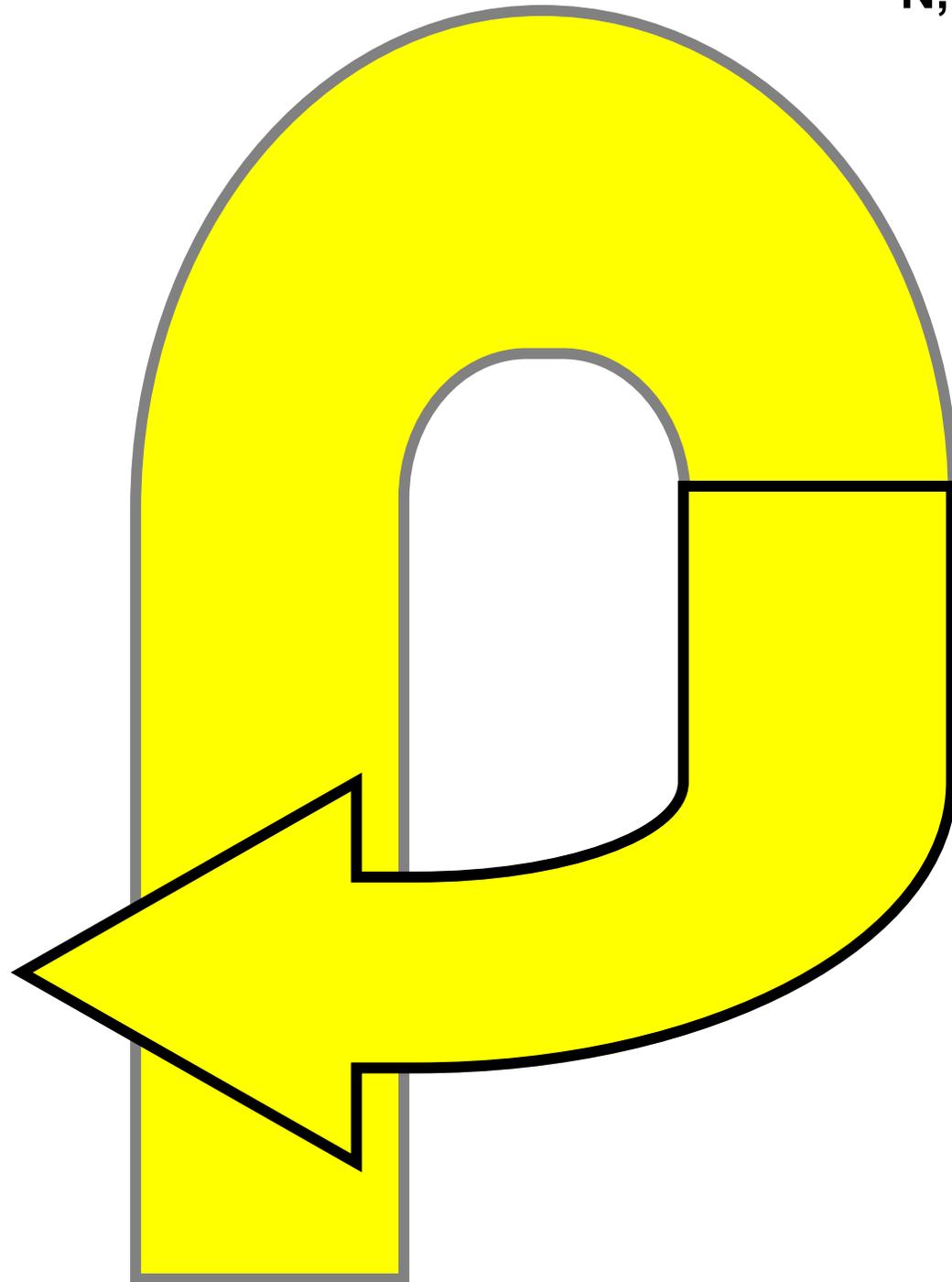


**About
“U”
Turn**





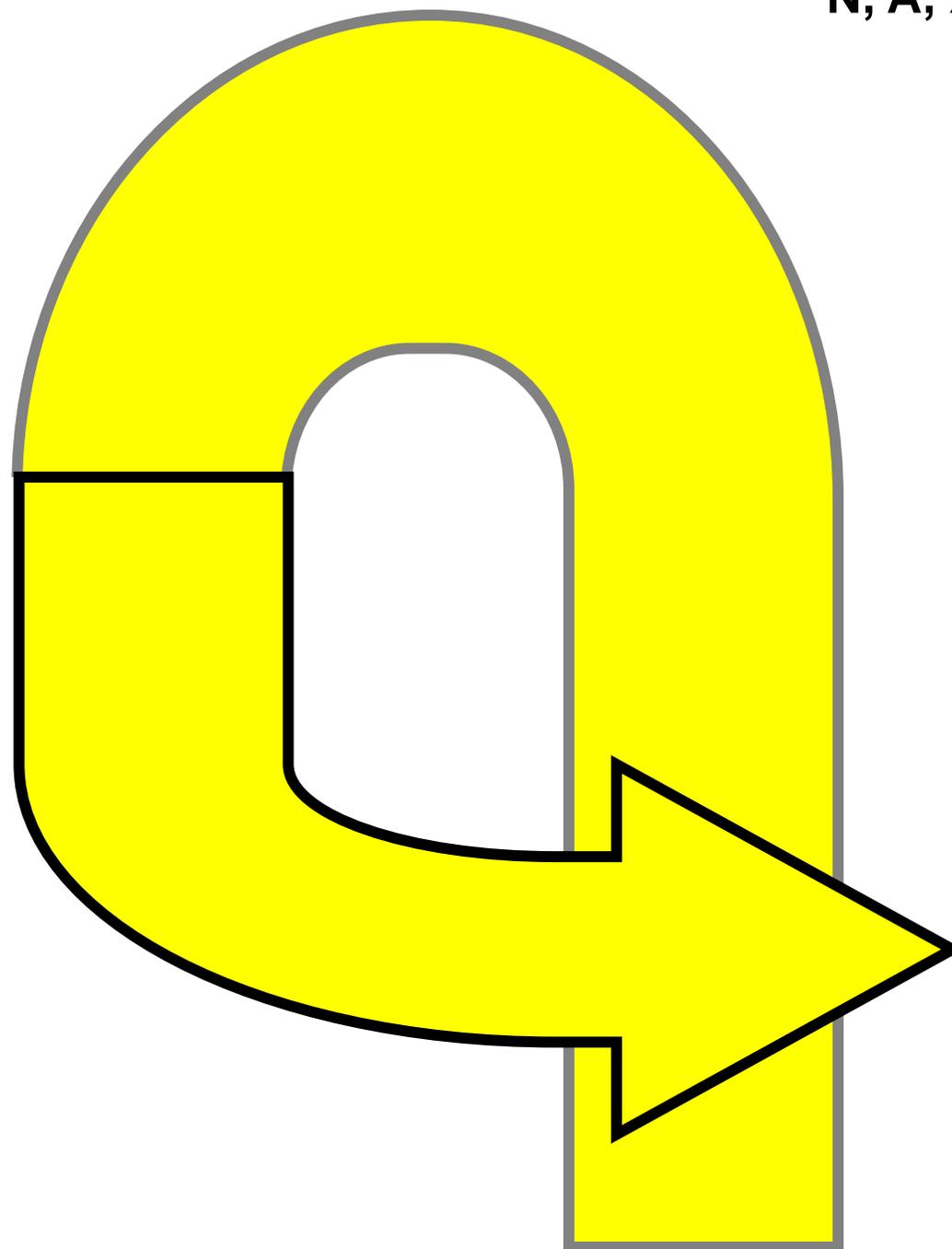
**270°
Right**

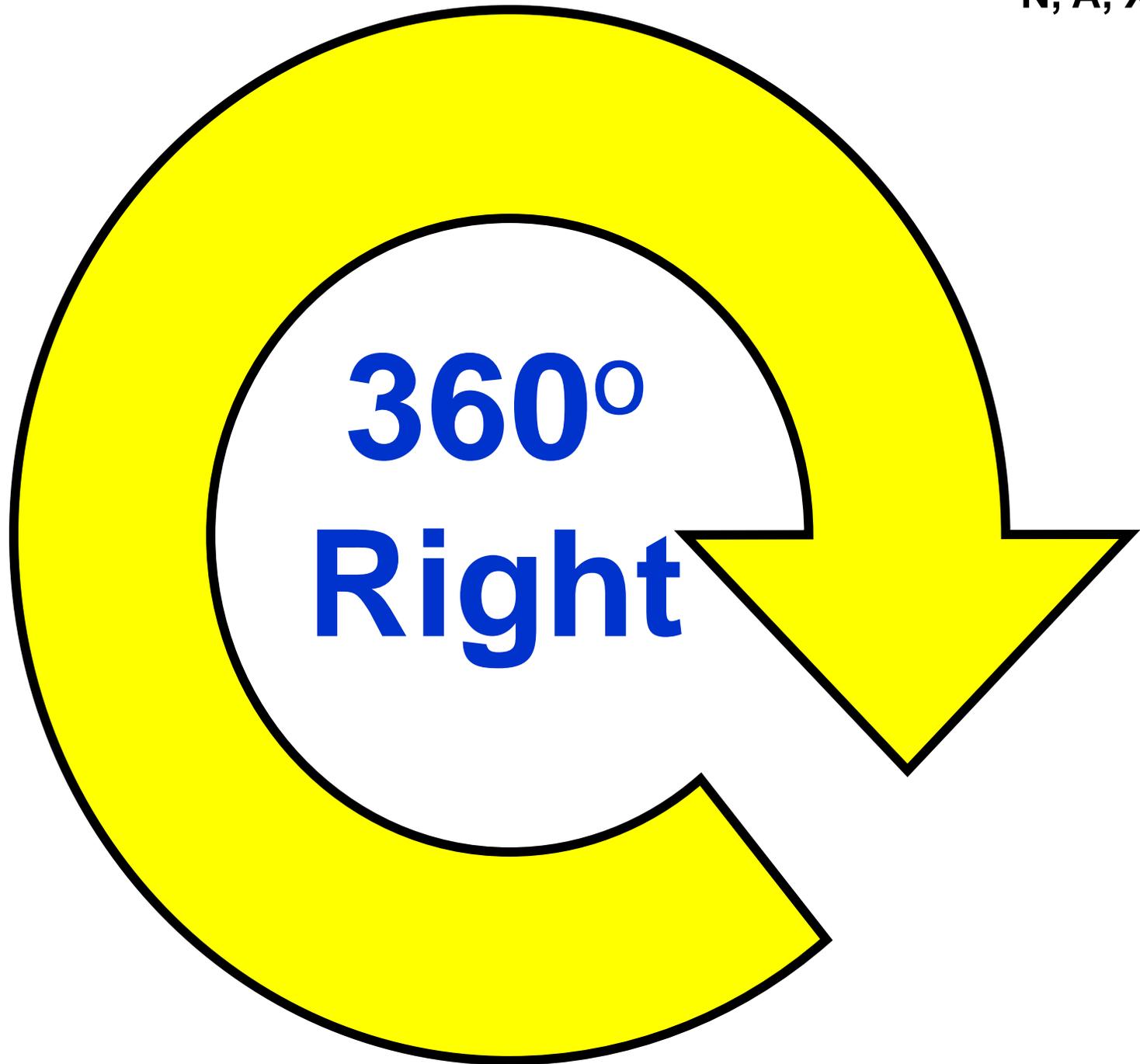


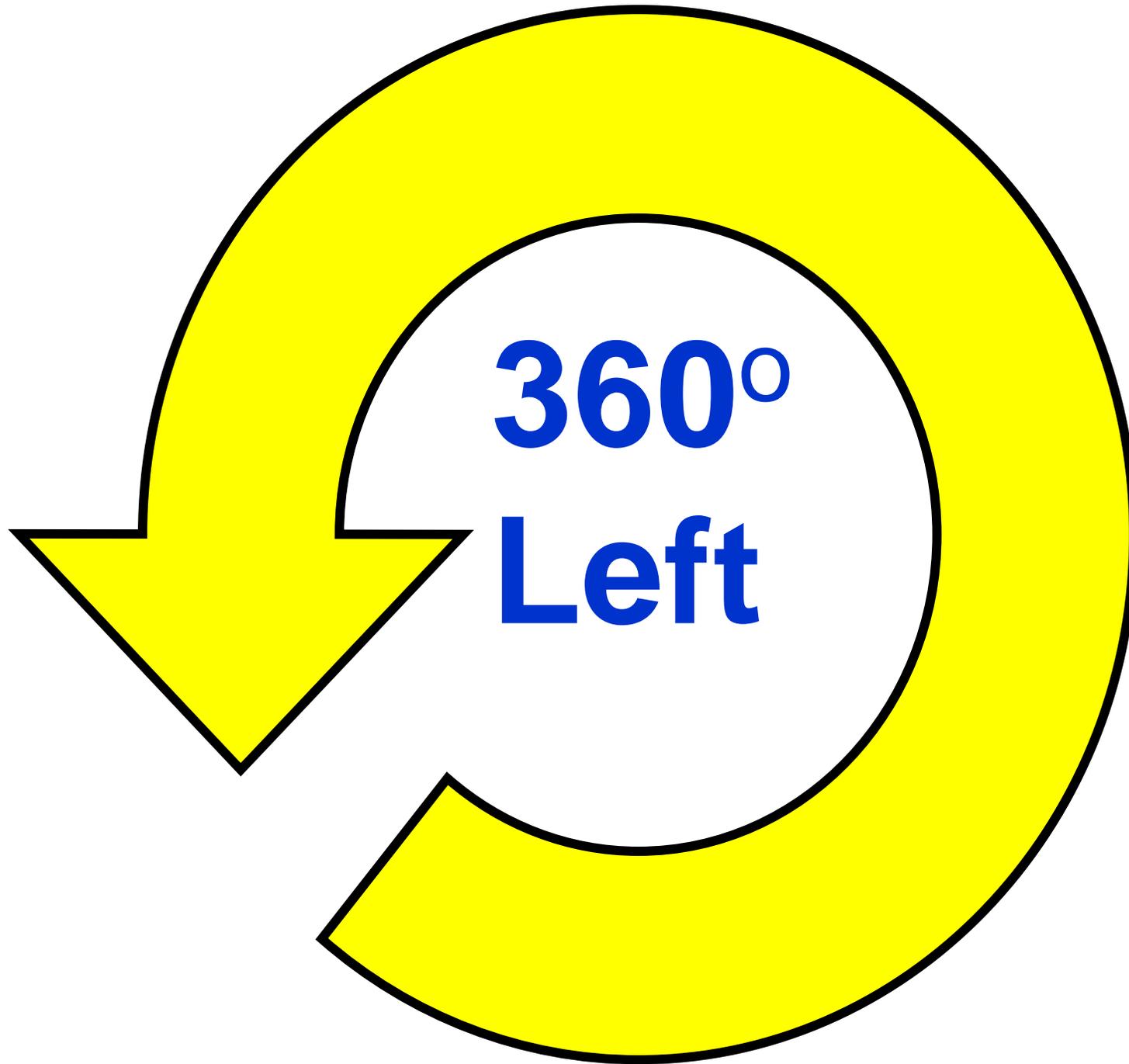


270°

Left

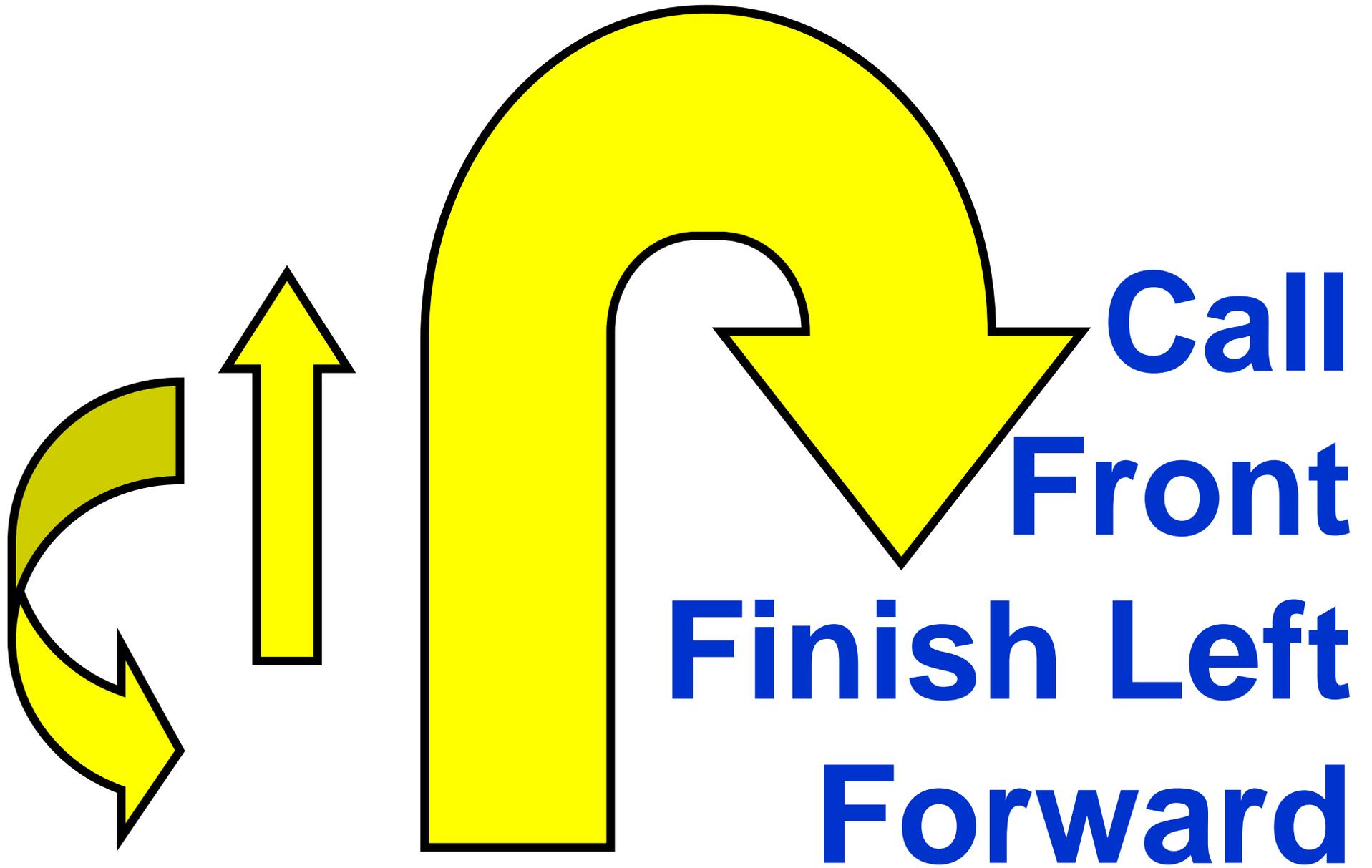








**Call
Front
Finish Right
Forward**



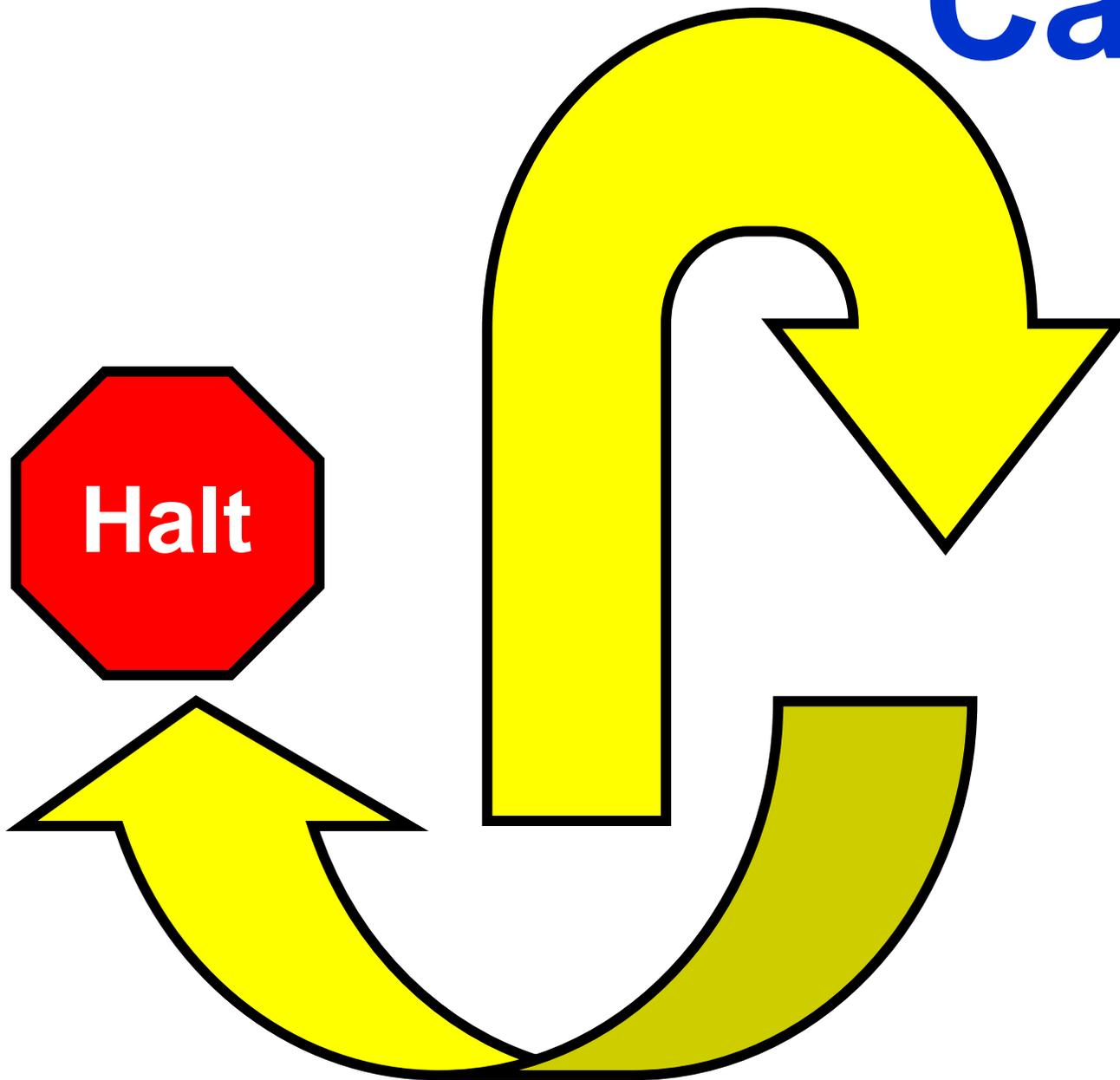


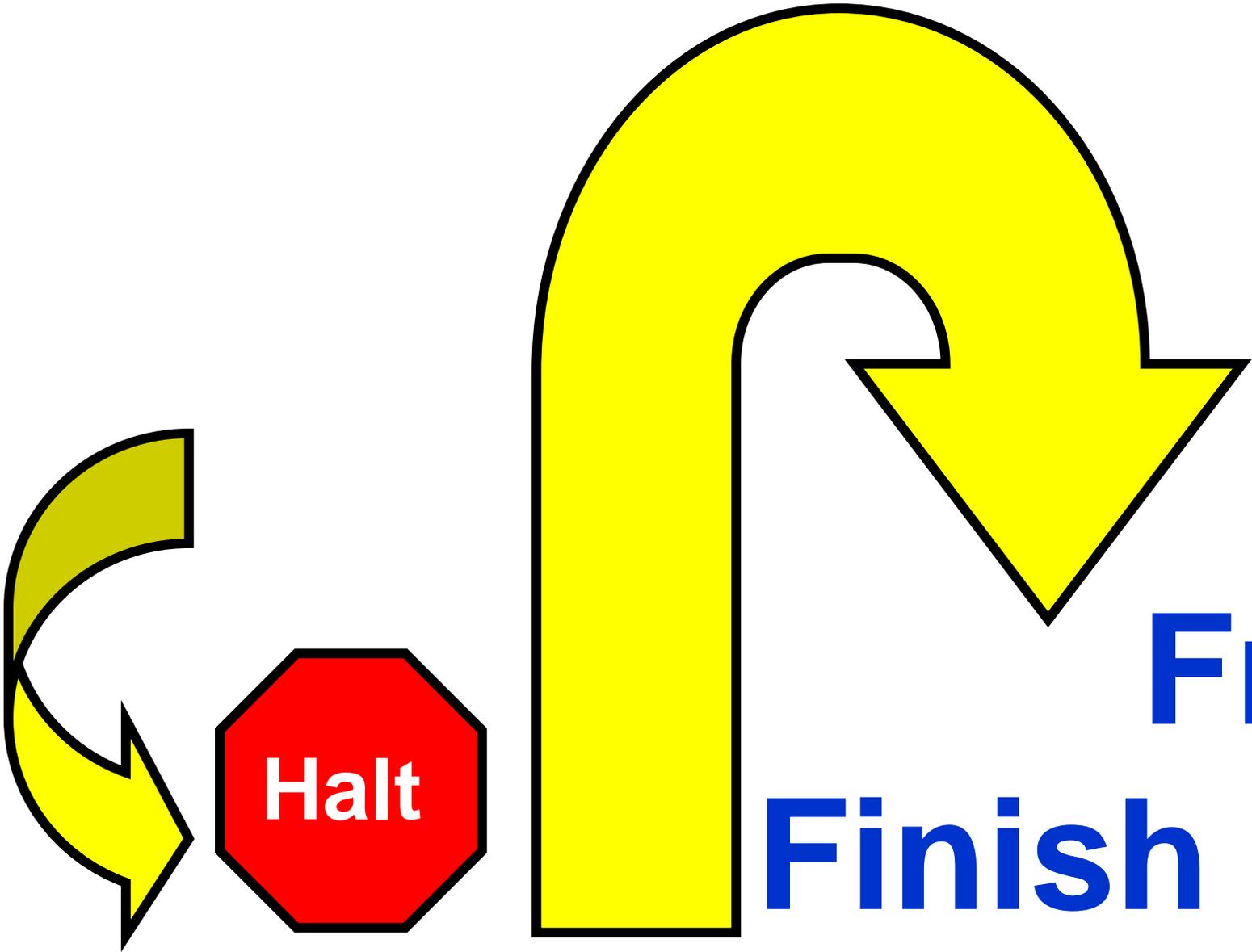
Call Front

Finish

Right

Halt

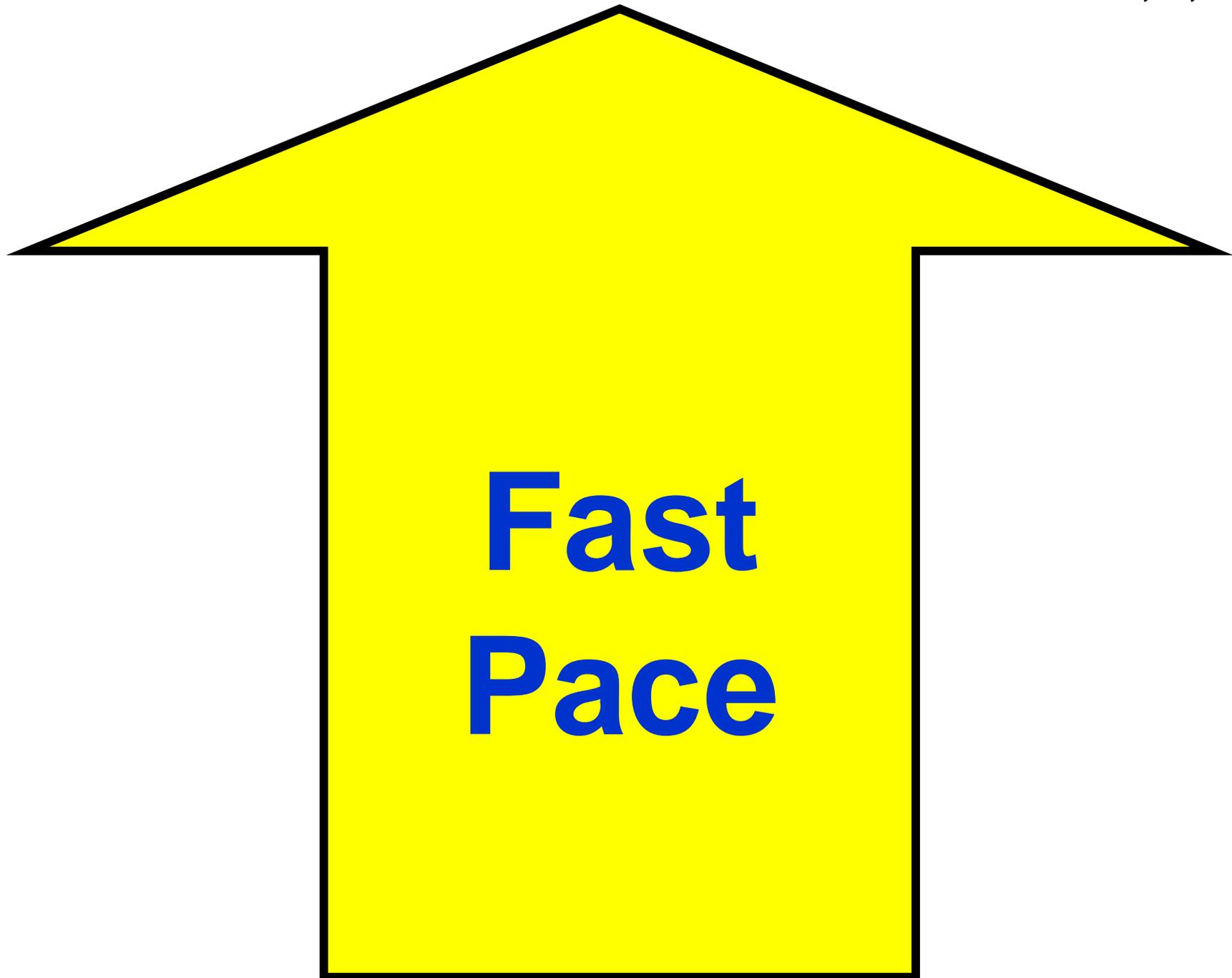




Call
Front
Finish Left
Halt



**Slow
Pace**



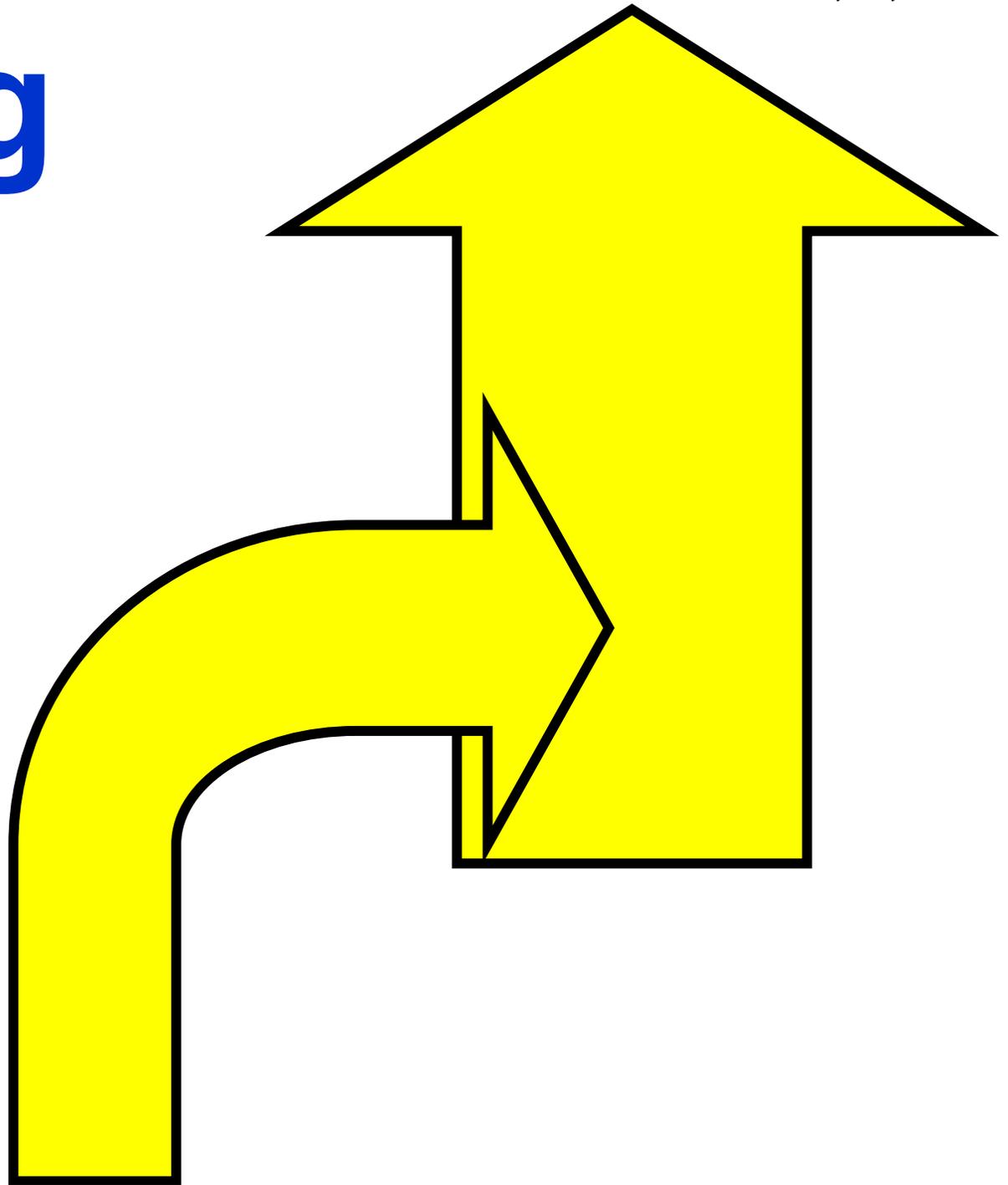
**Fast
Pace**

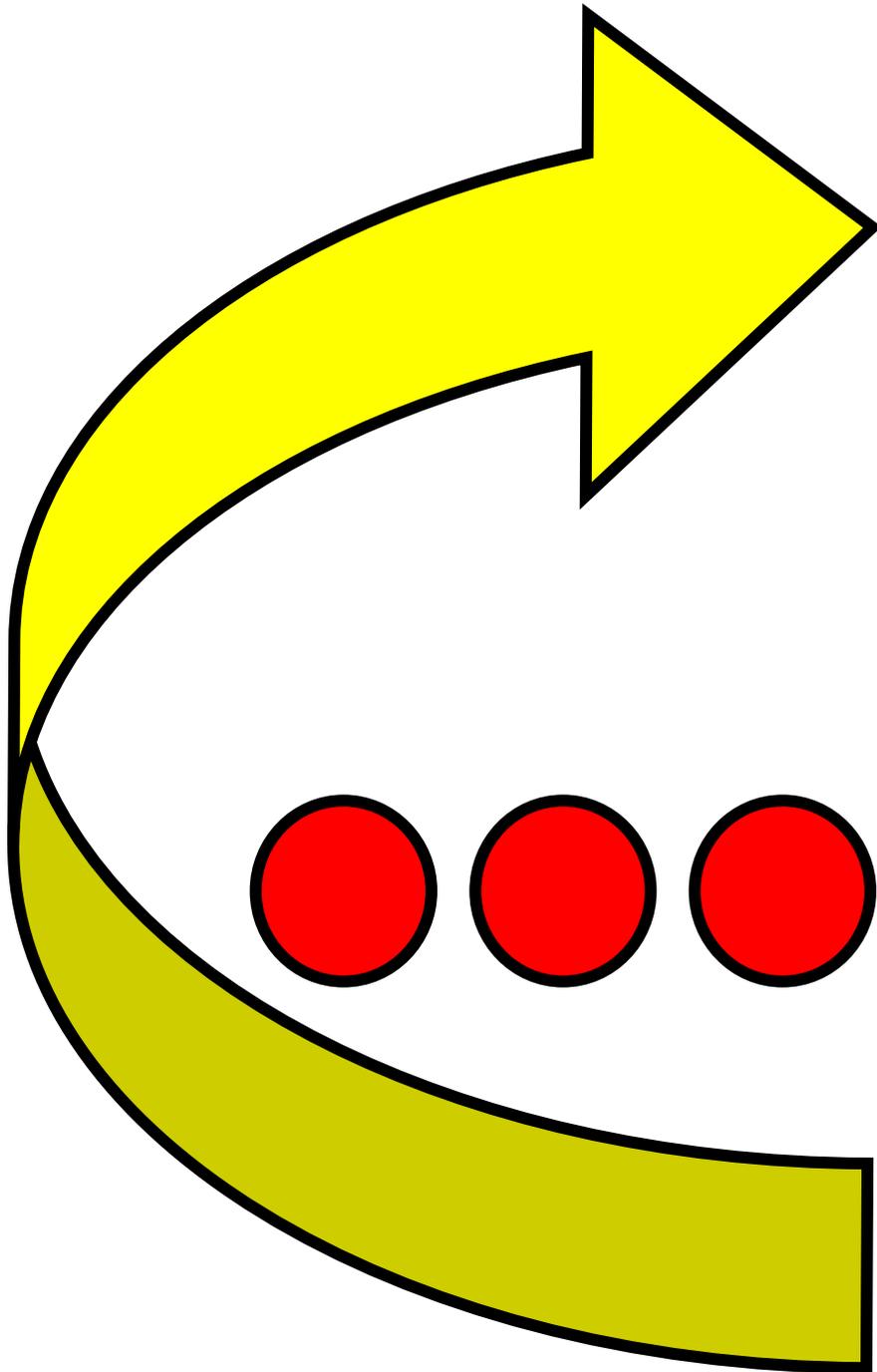


**Normal
Pace**



**Moving
Side
Step
Right**



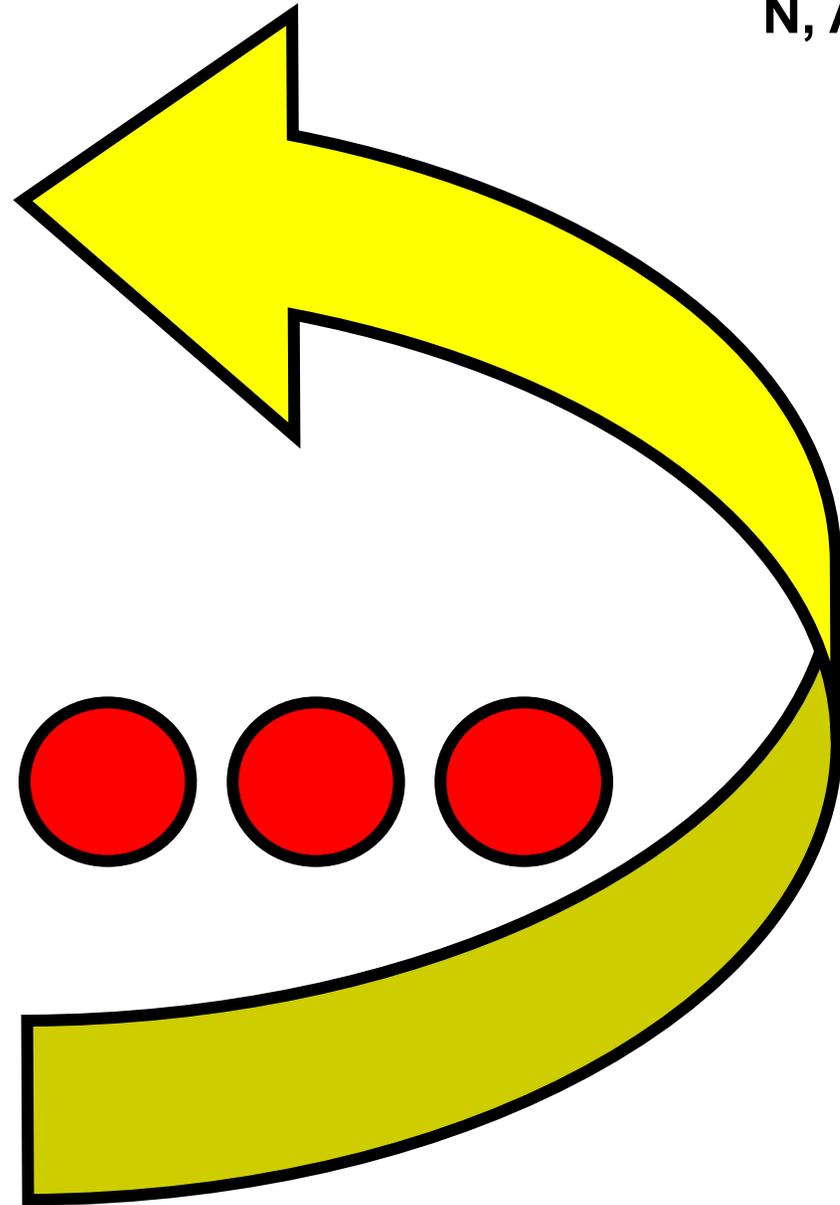


**Spiral
Right**

**Dog
Outside**

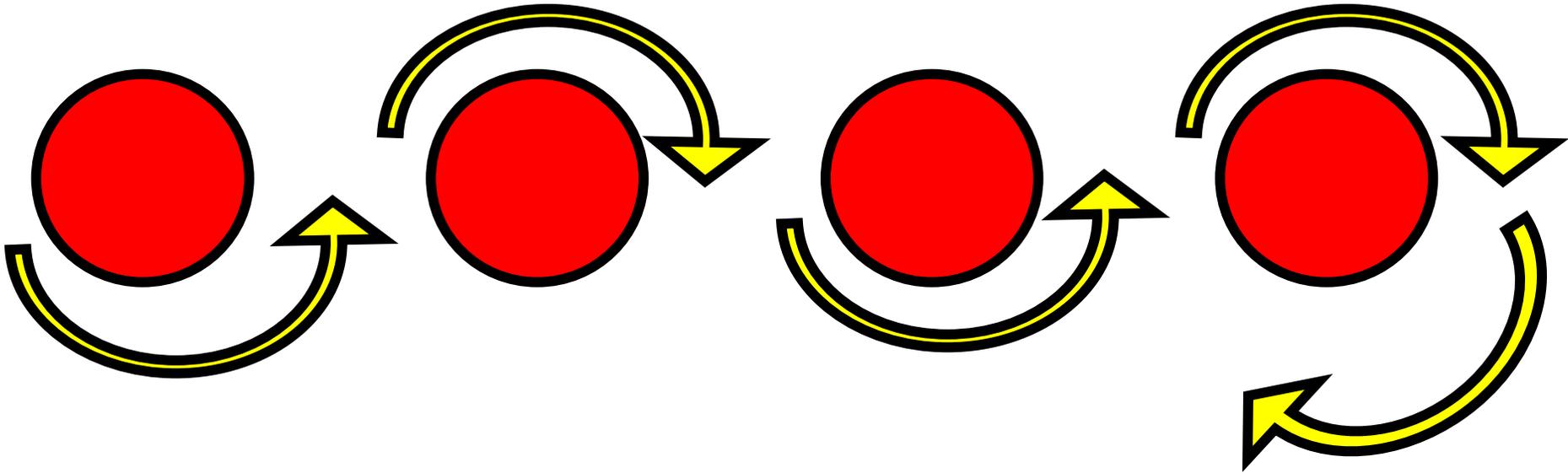


**Spiral
Left**

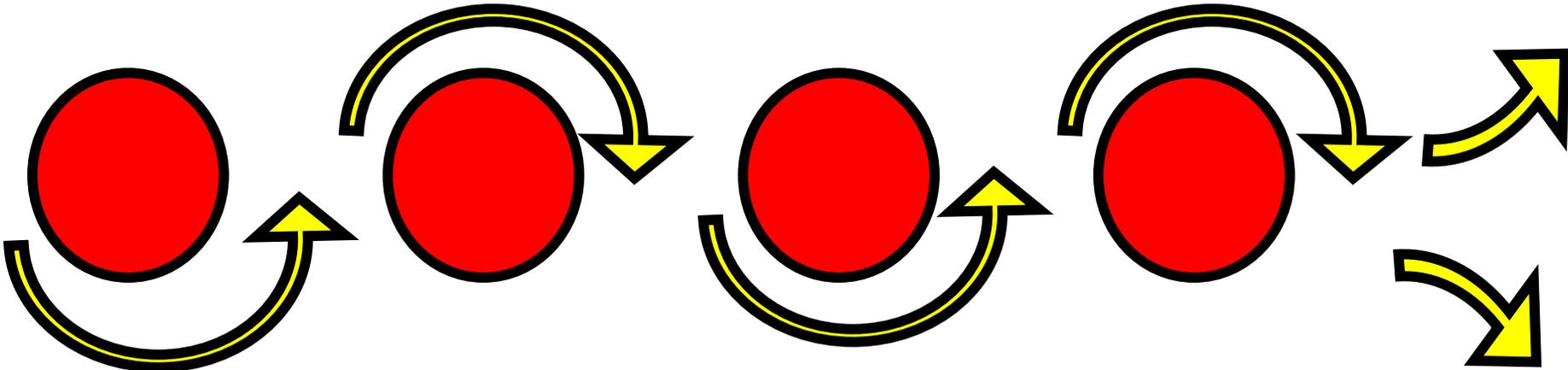


Dog Inside

Straight Figure 8 Weave Twice

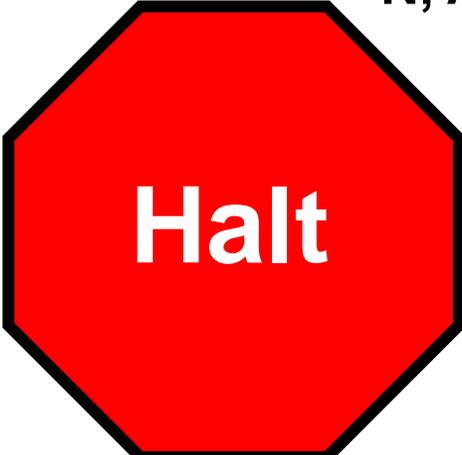


Serpentine Weave Once





1 Step



2 Steps



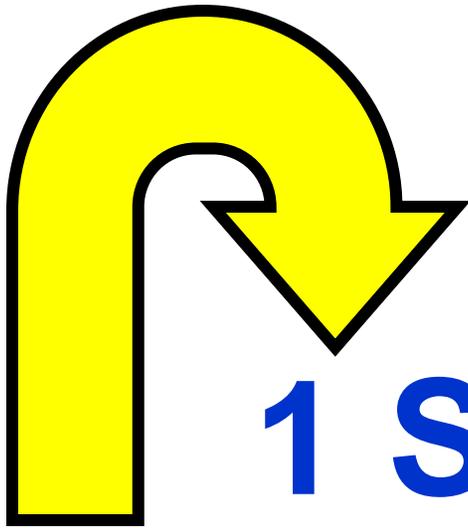
3 Steps





Call Front

N, A, X- #26



1 Step Back

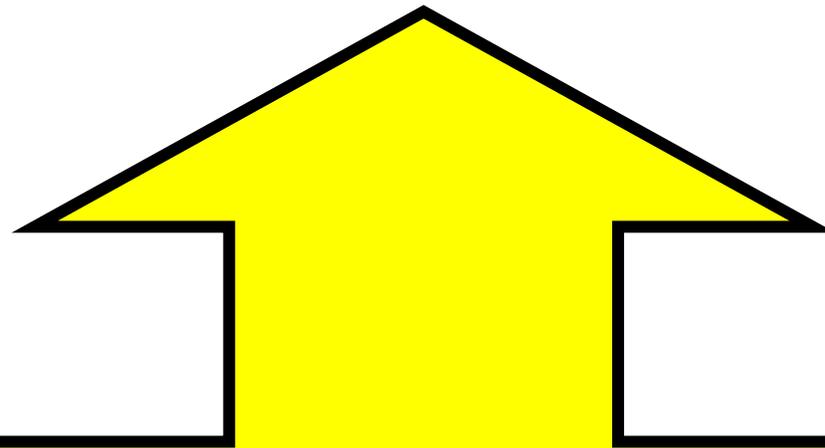


2 Steps Back

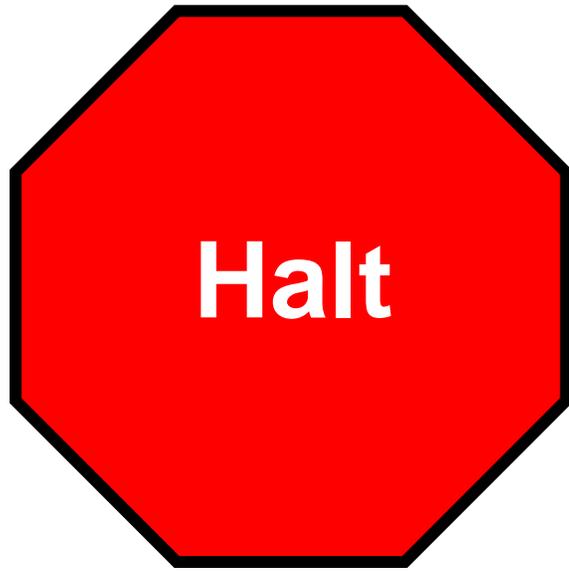


3 Steps Back

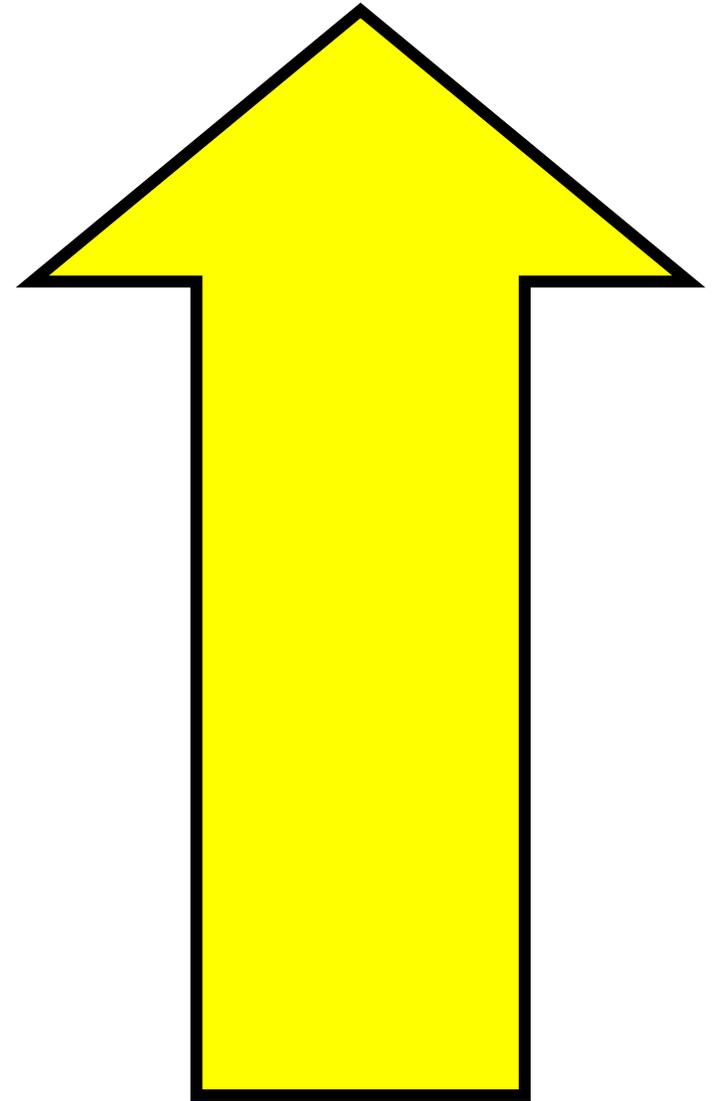




**Down
and
Stop**

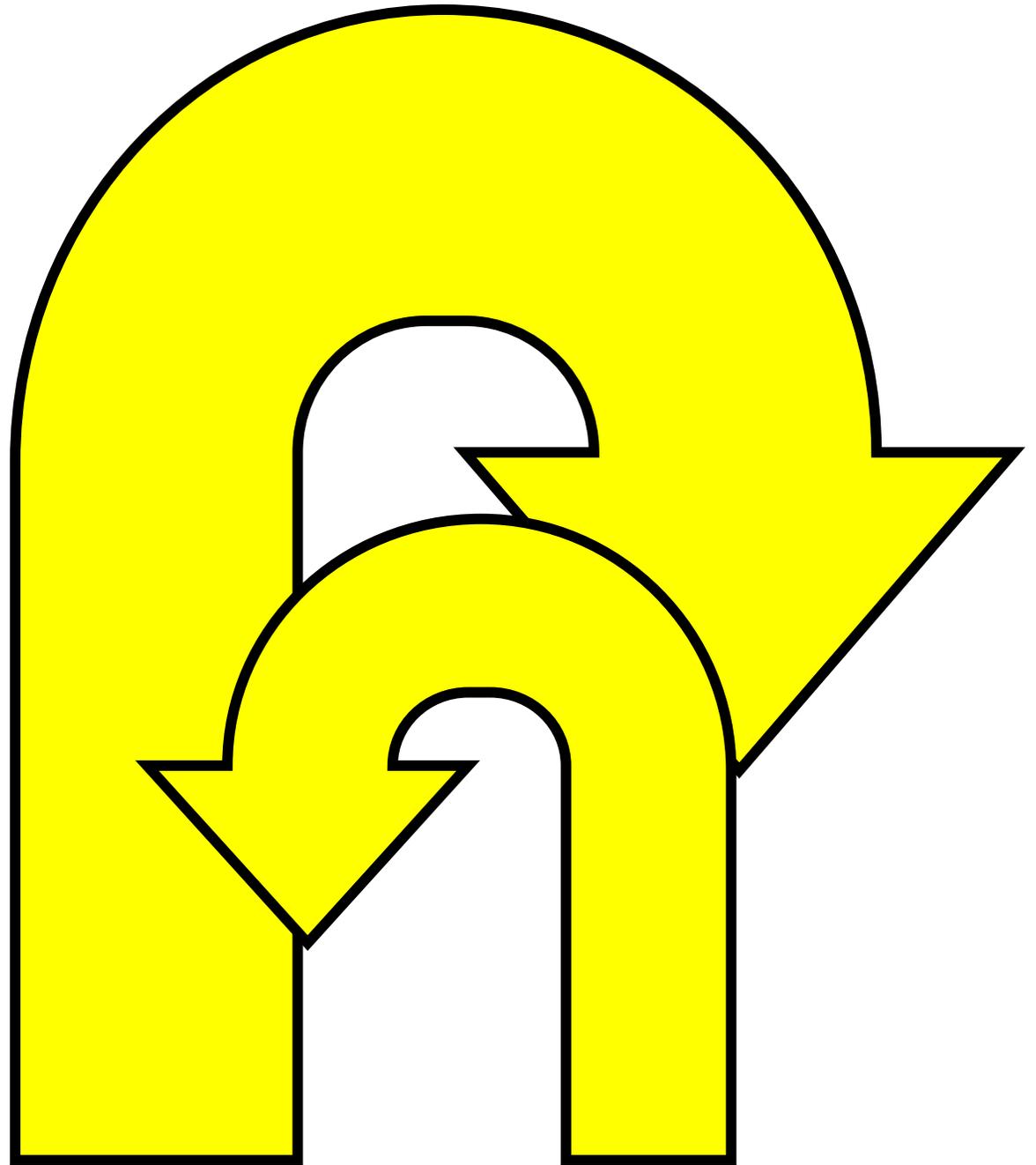


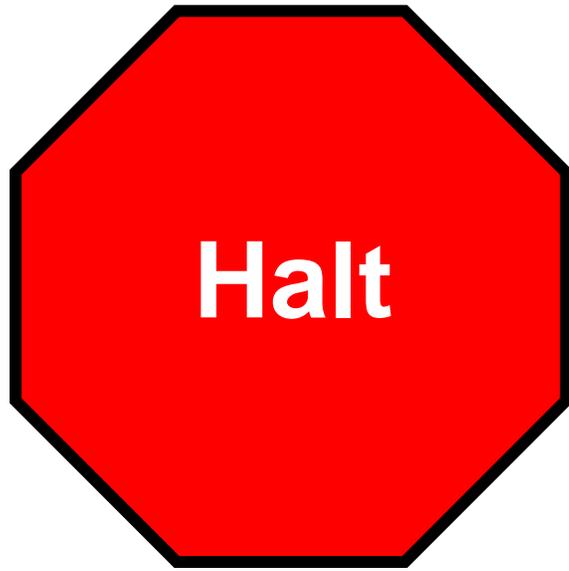
**Fast
Forward
From Sit**





**Left
About
Turn**







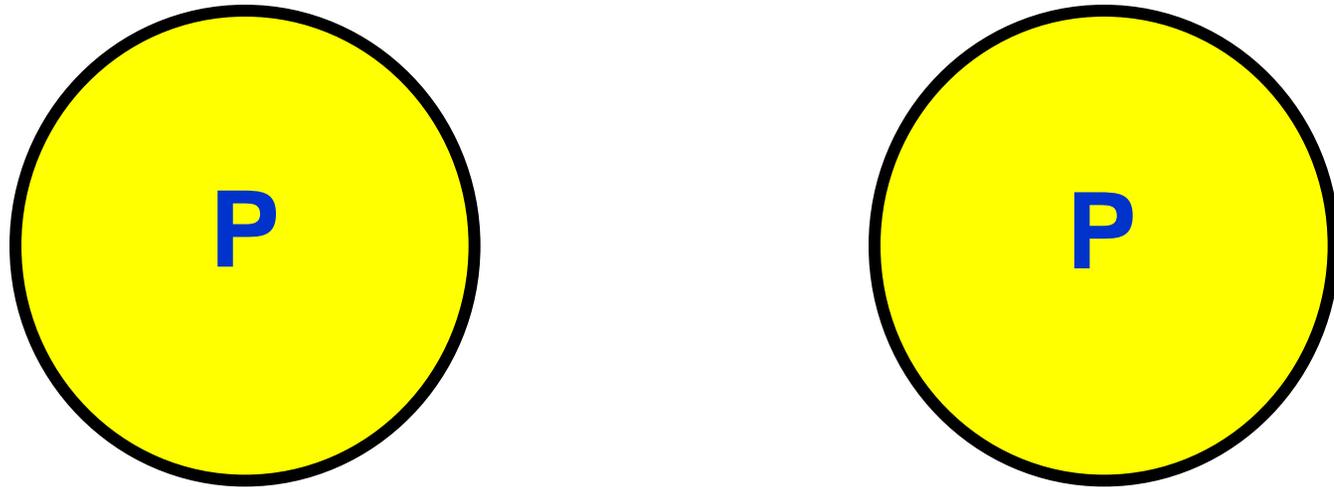
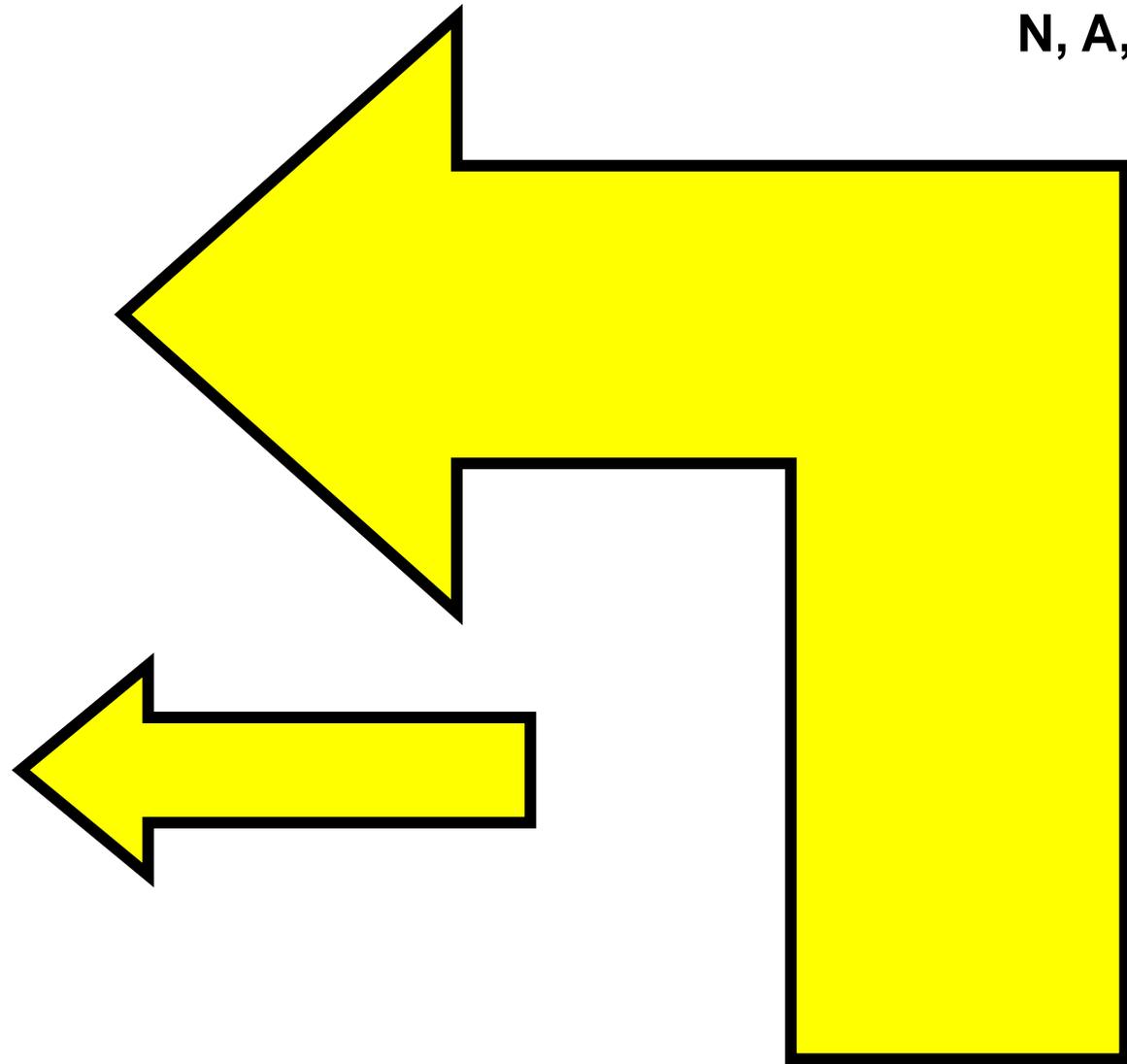
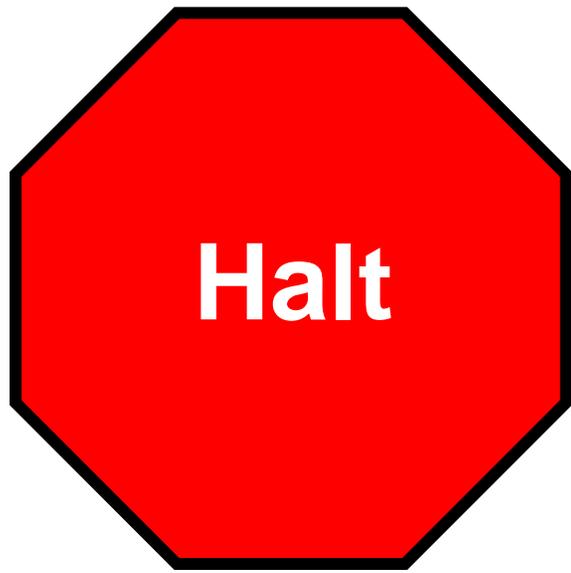
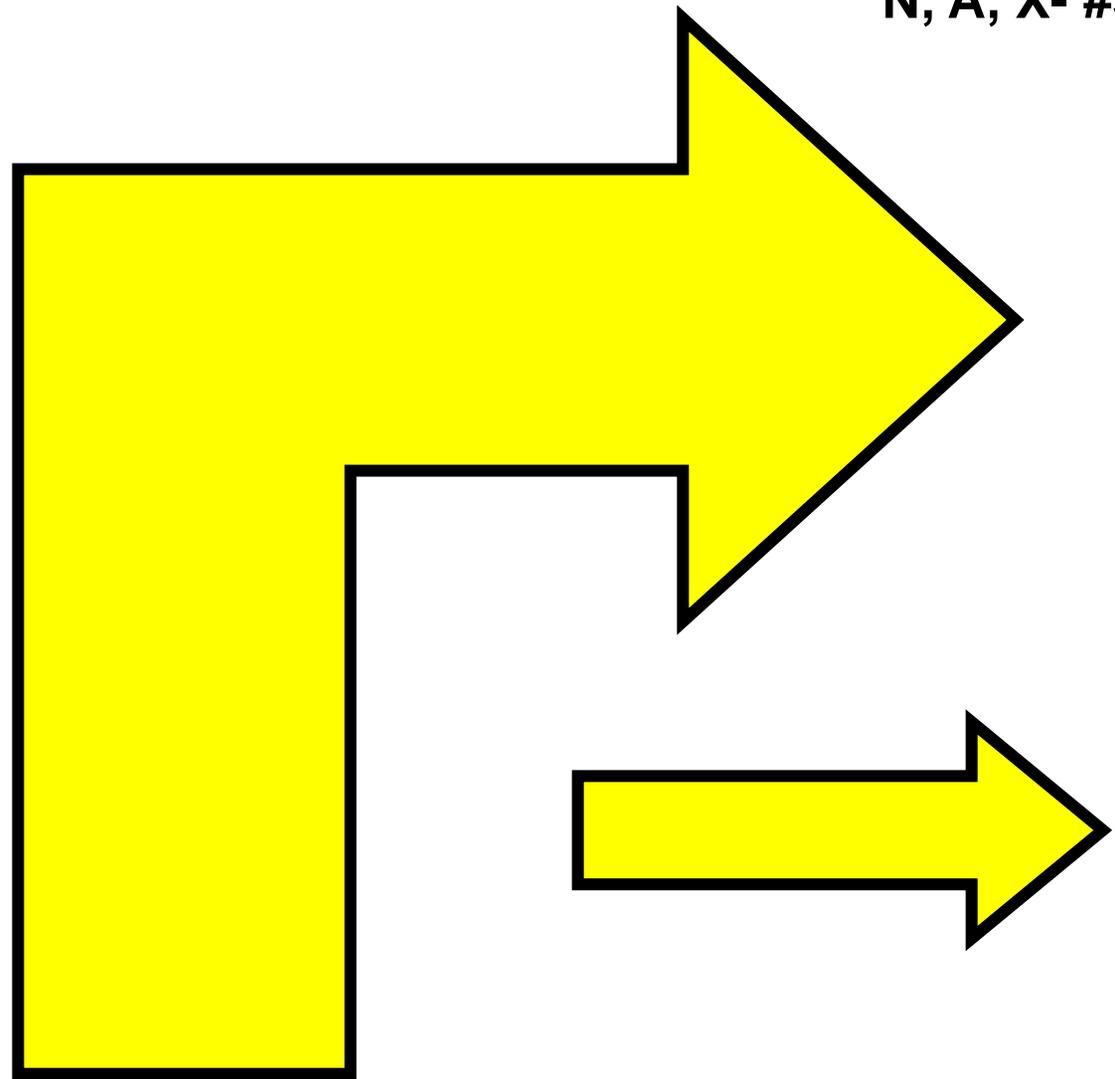


Figure 8
No Distractions



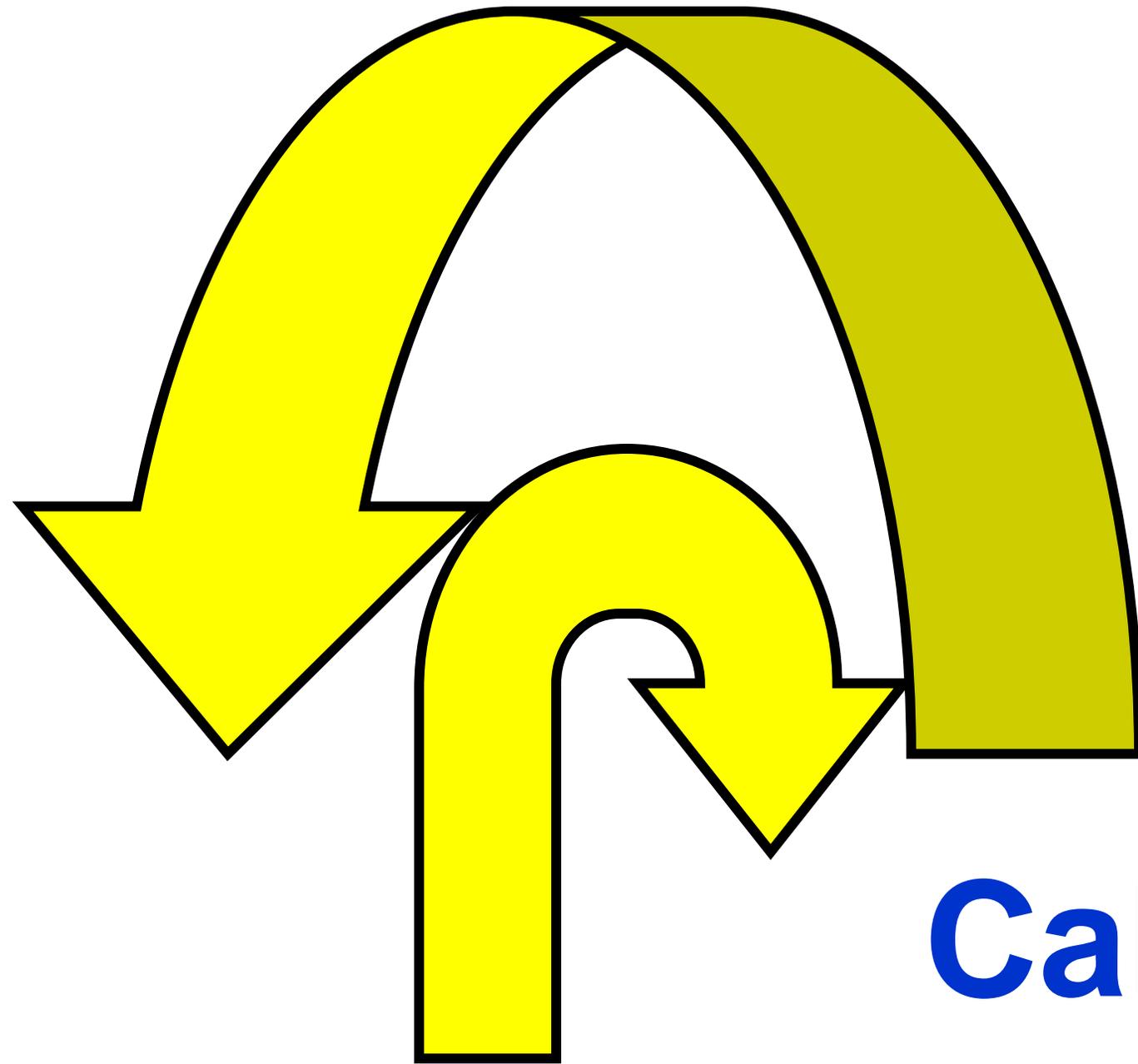
Left

Turn - Forward

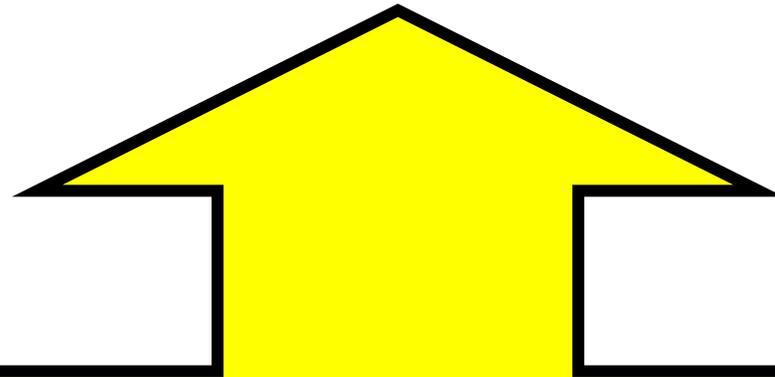
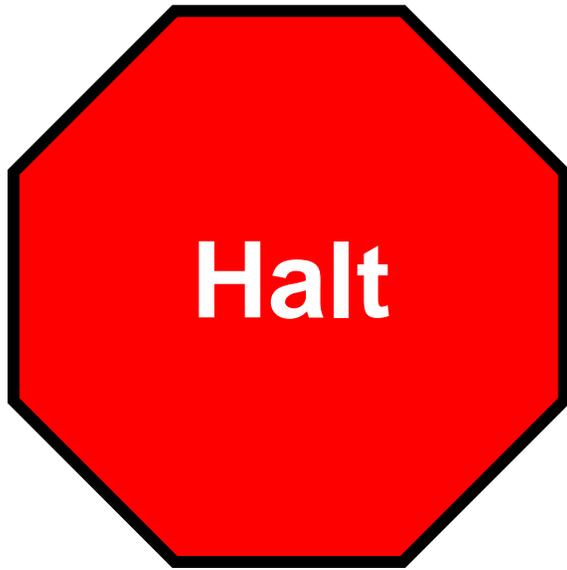


Right

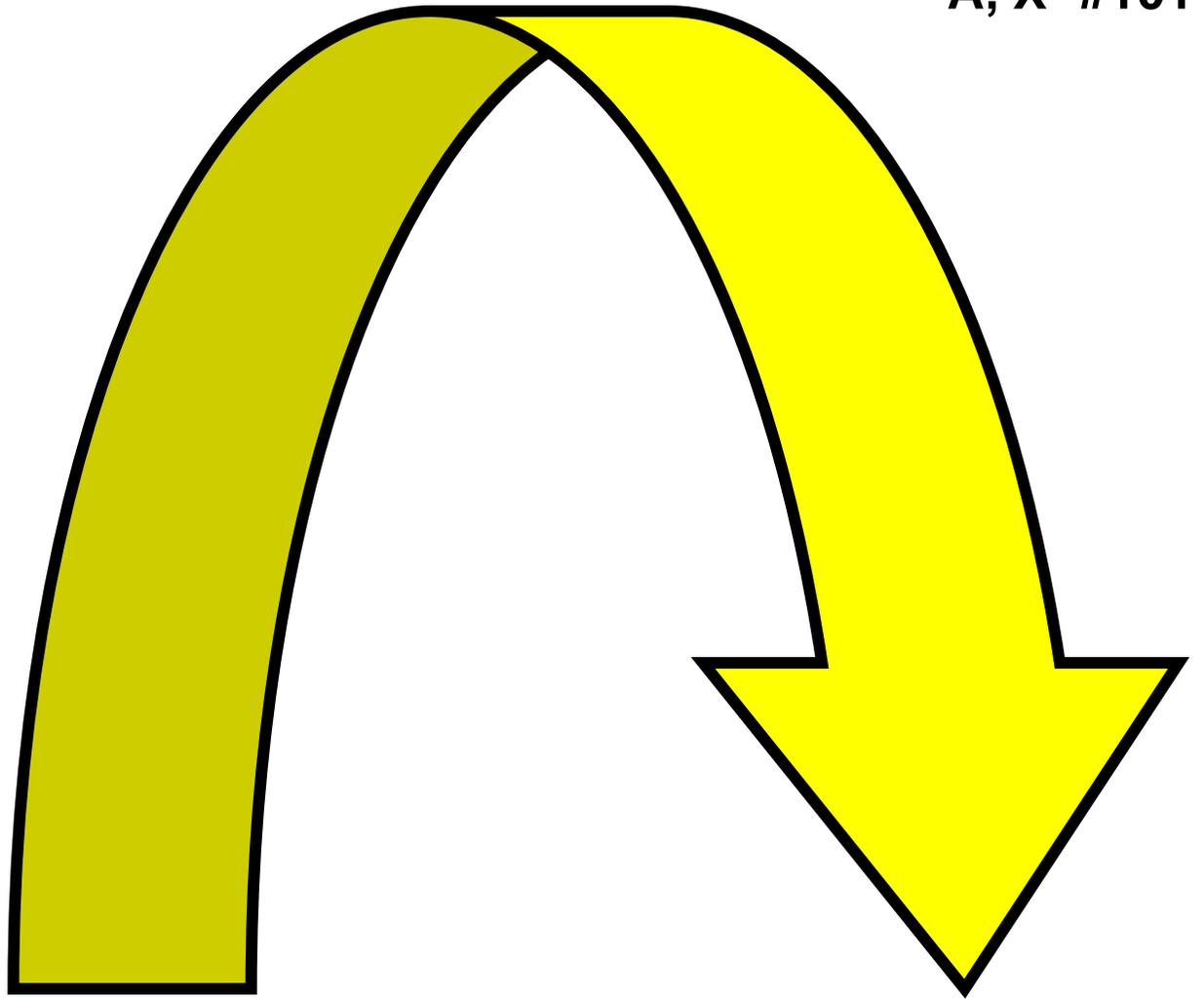
Turn - Forward



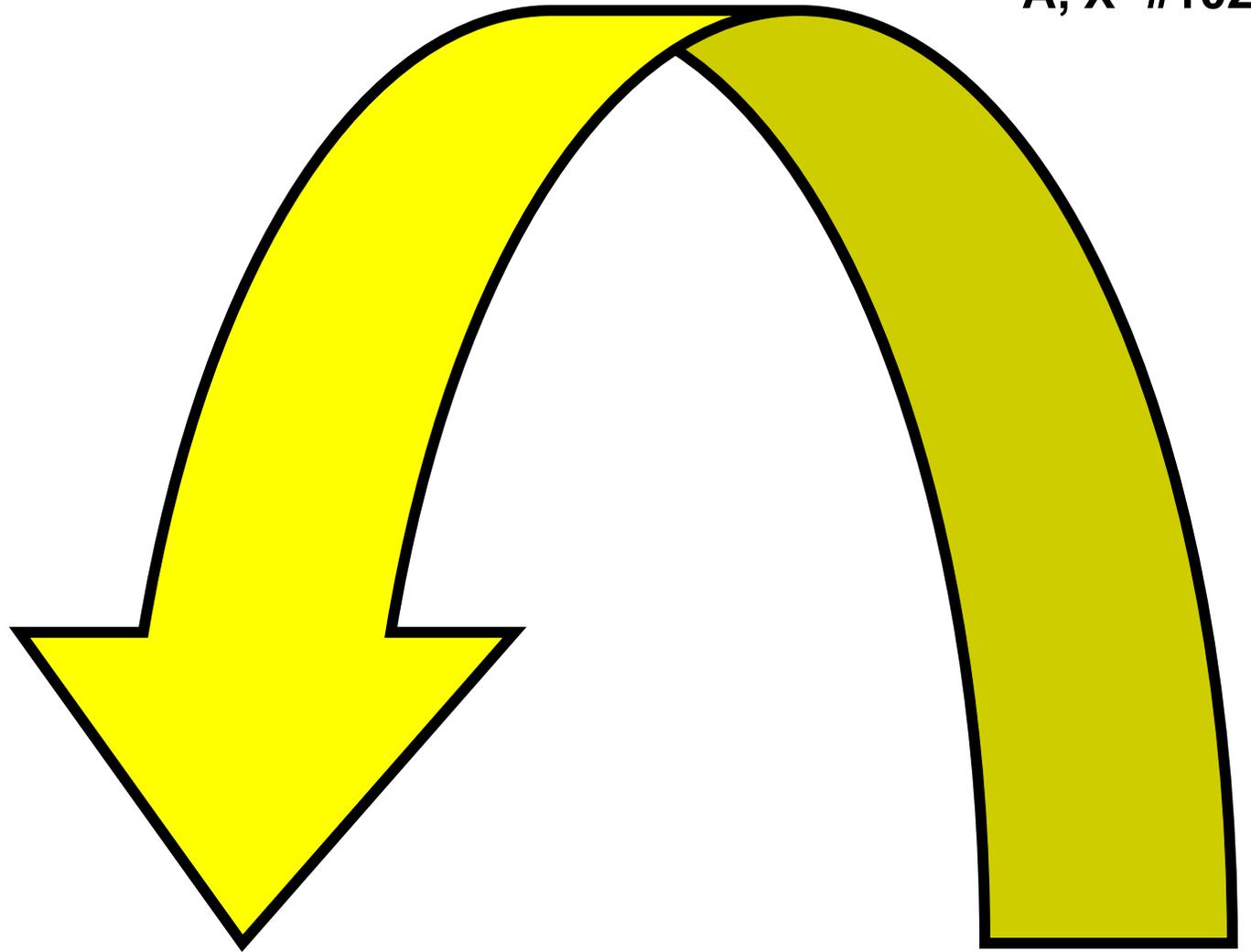
Call Front
Return to Heel



**Slow Forward
From Sit**

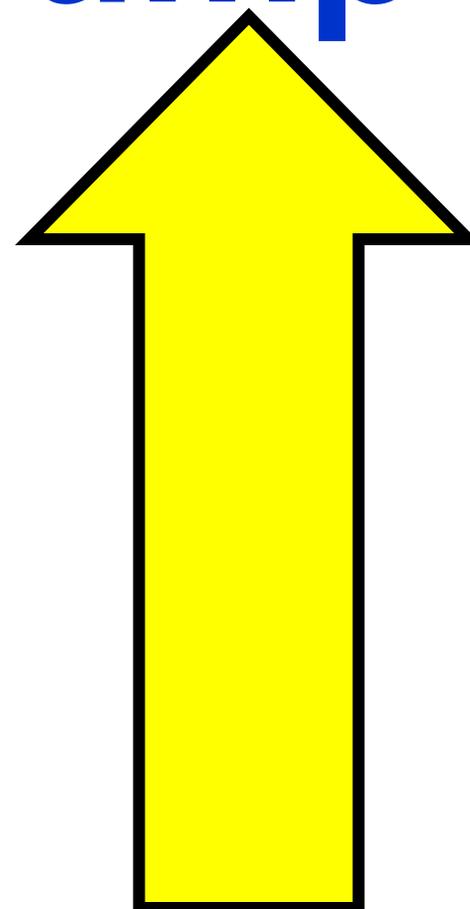
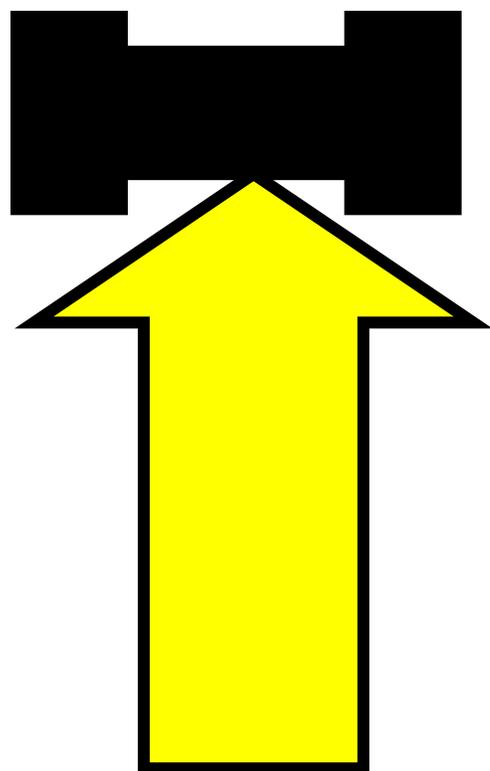


**About Turn Right
Forward**

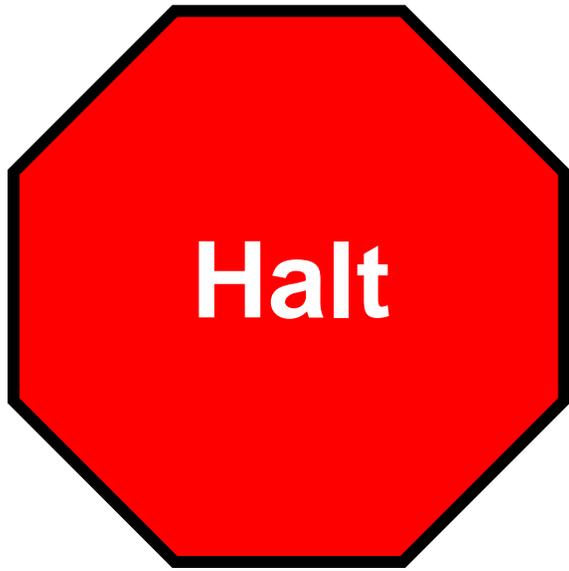


**About “U” Turn
Forward**

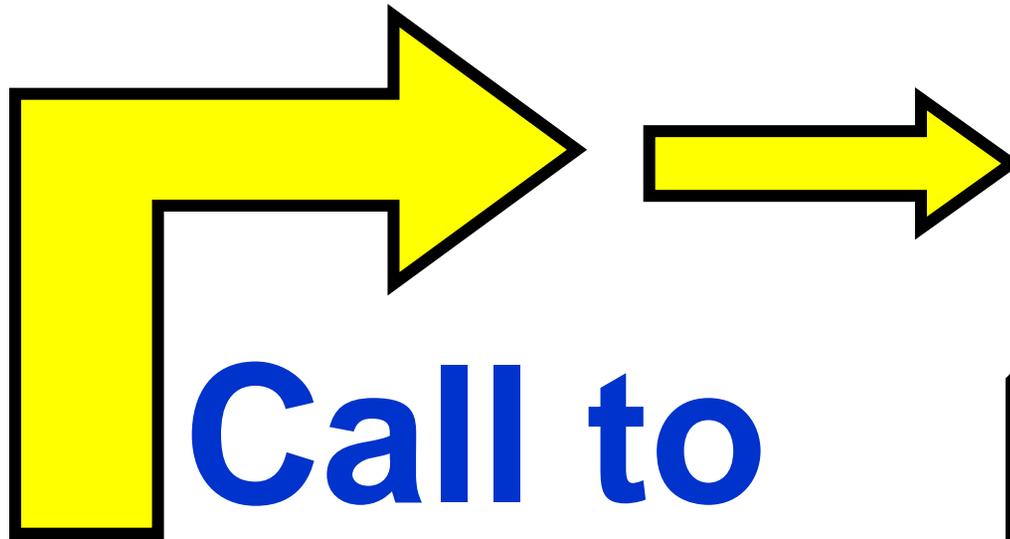
Send Over Jump



Handler Passes By



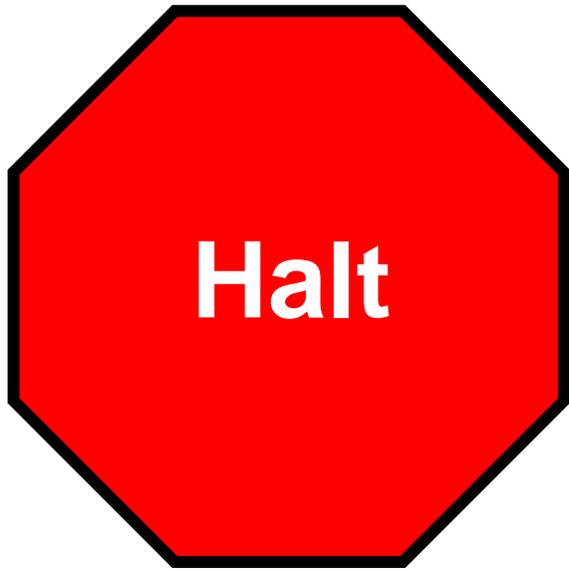
**Turn Right
1 Step**



**Call to
Heel**



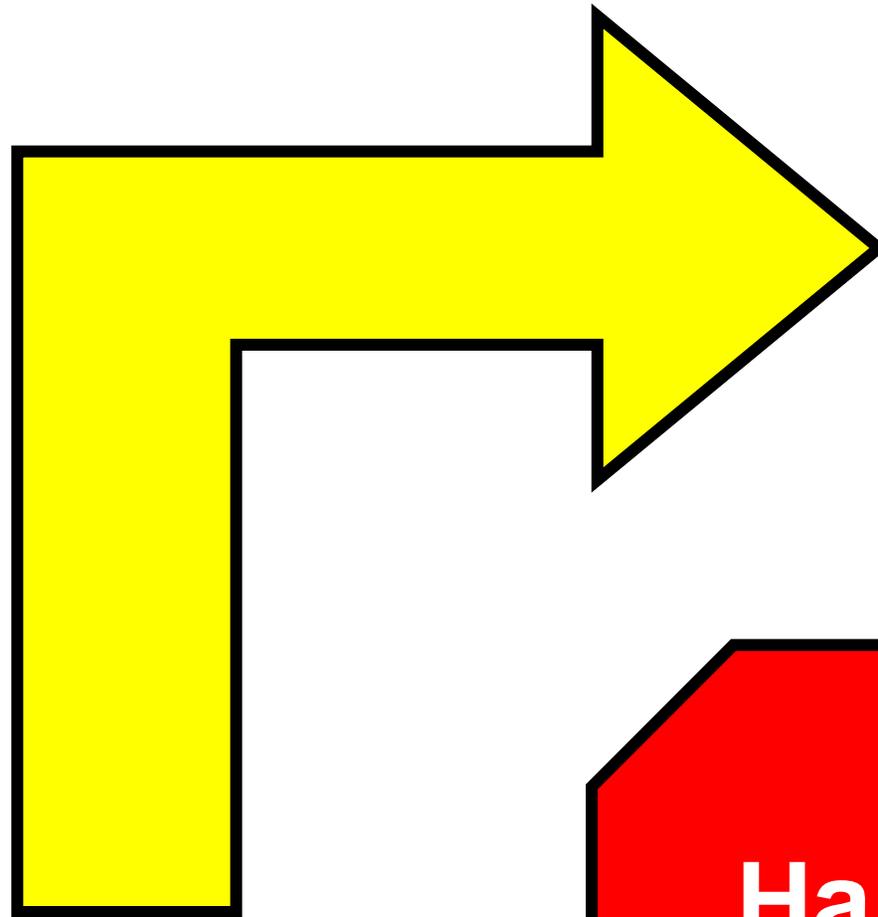


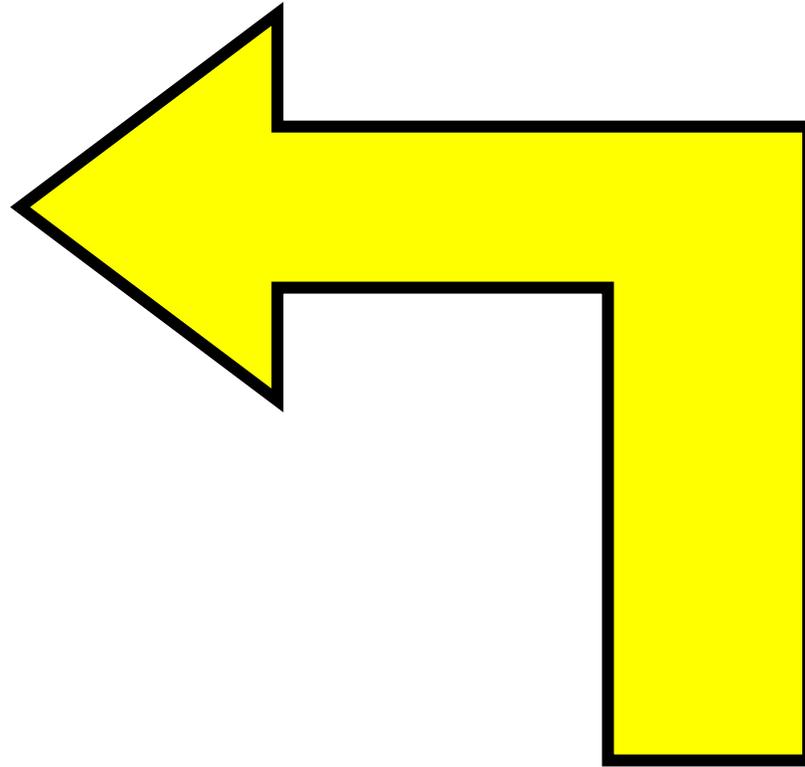
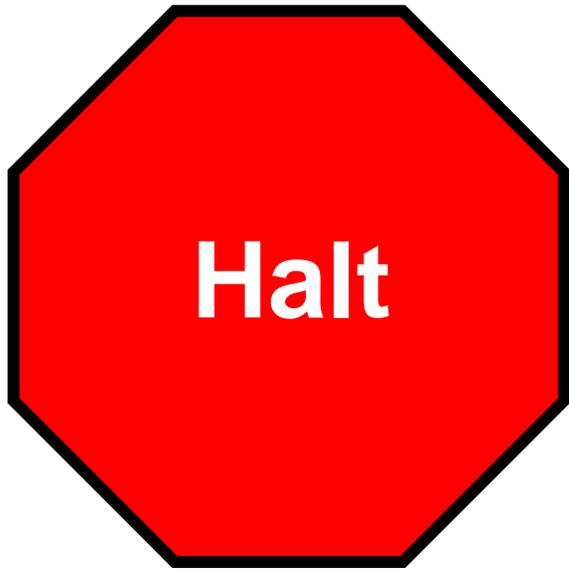


90°

Pivot

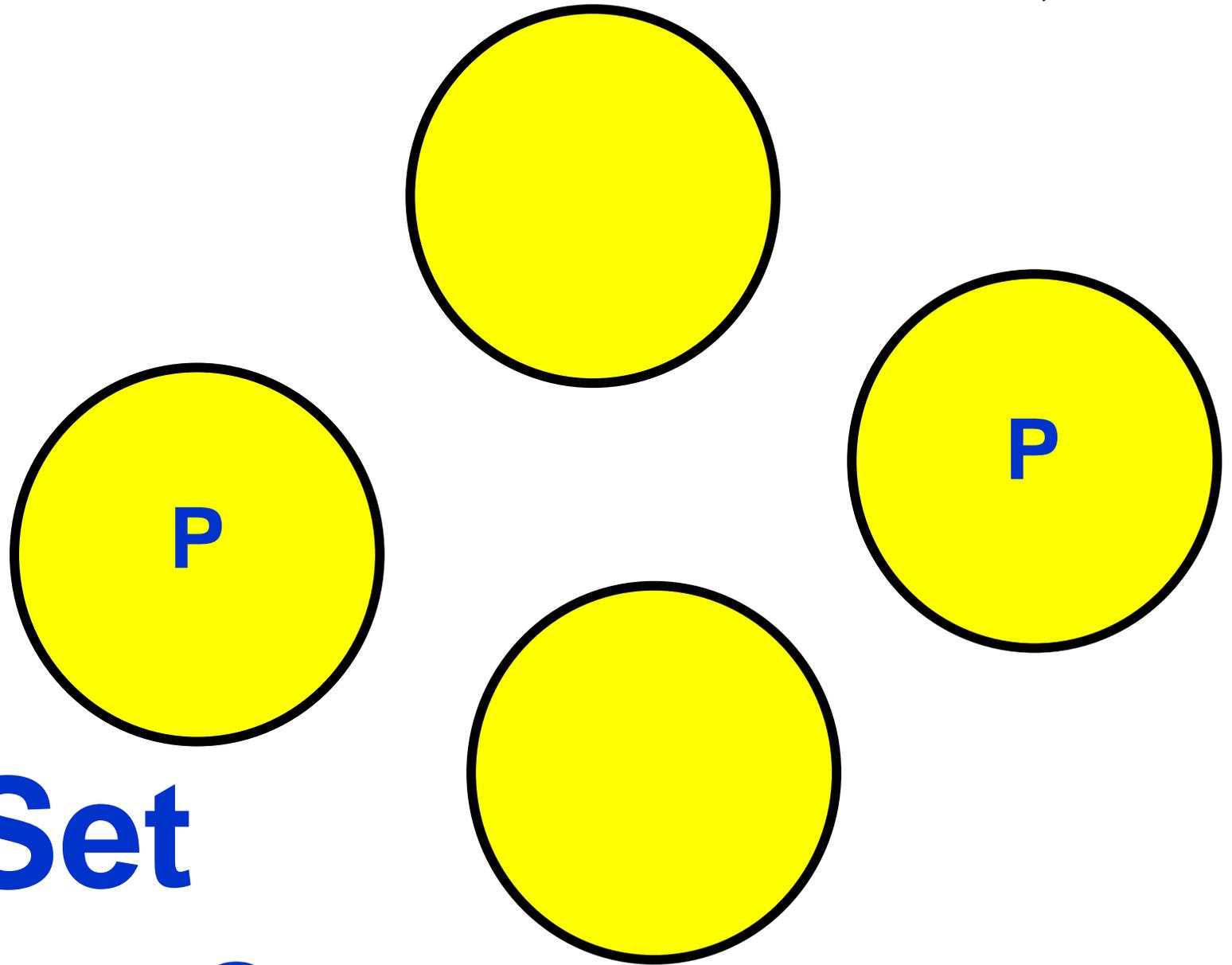
Right



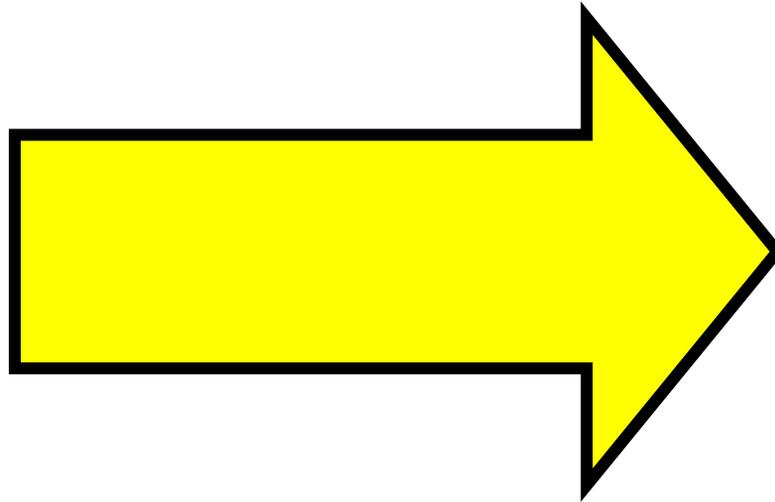


**90°
Pivot
Left**



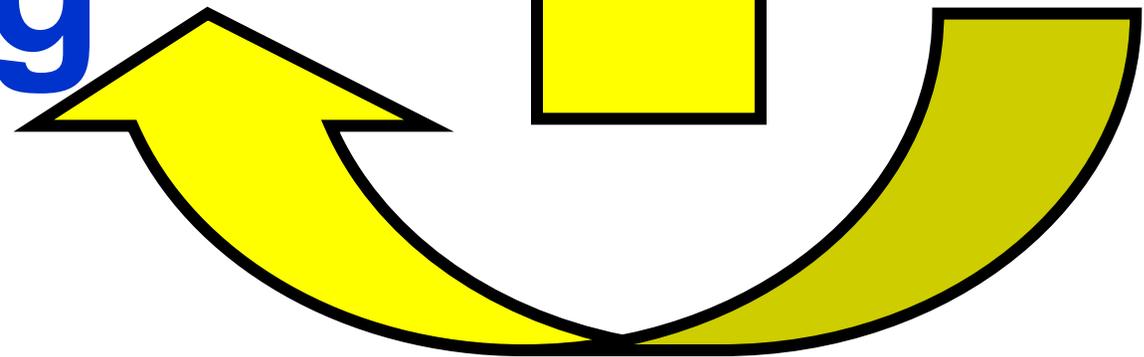
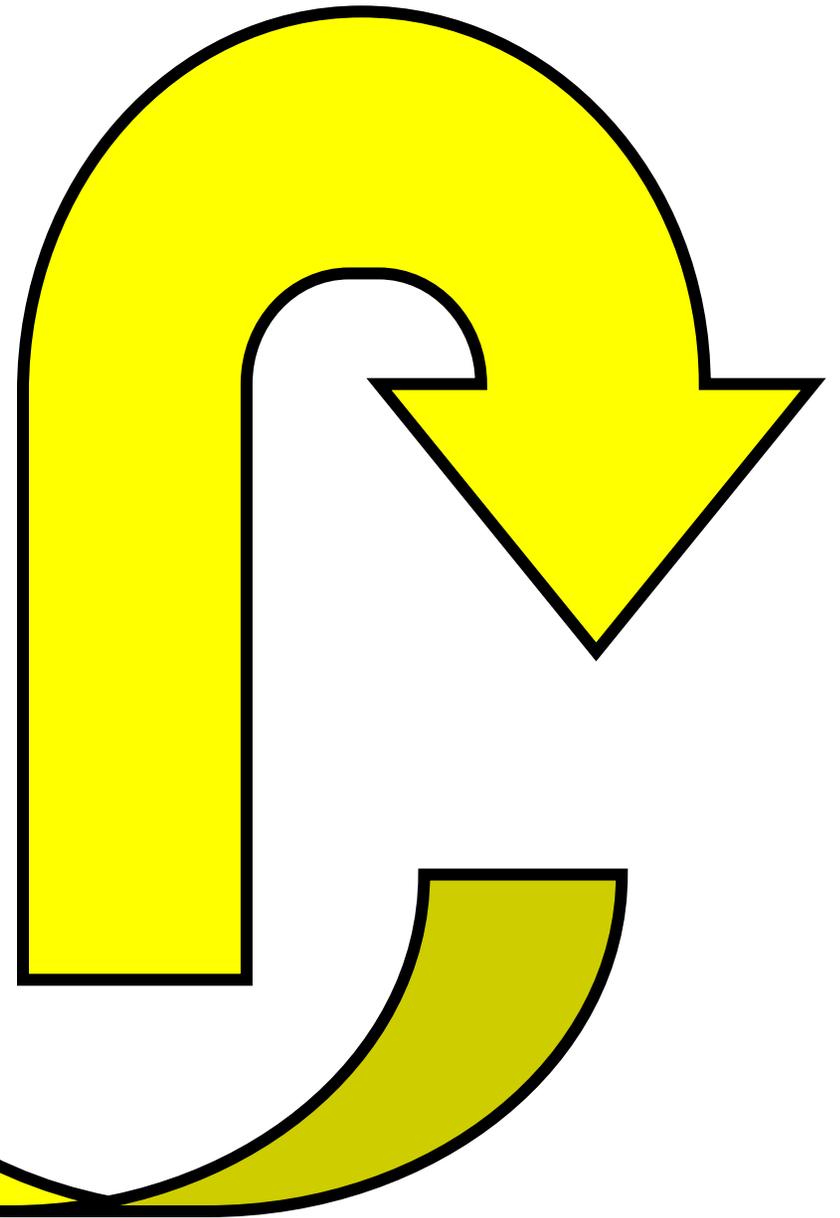
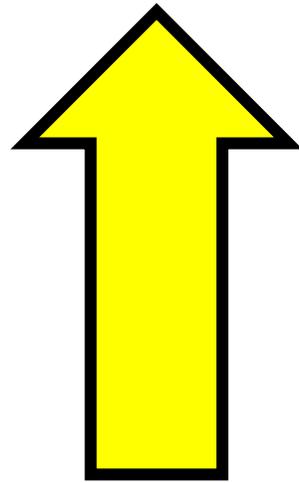
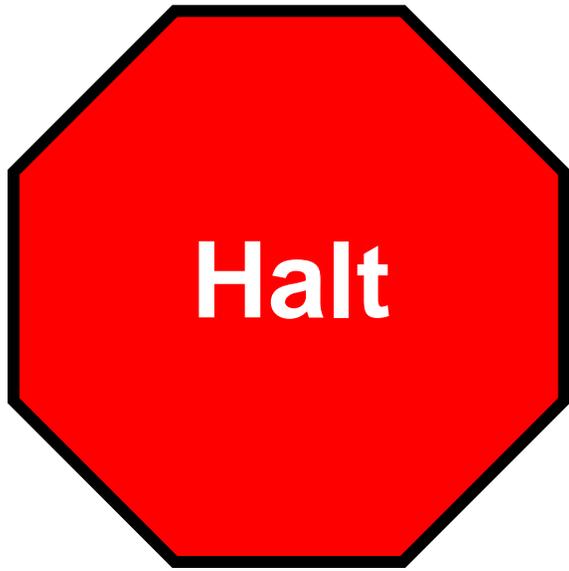


Off-Set Figure 8

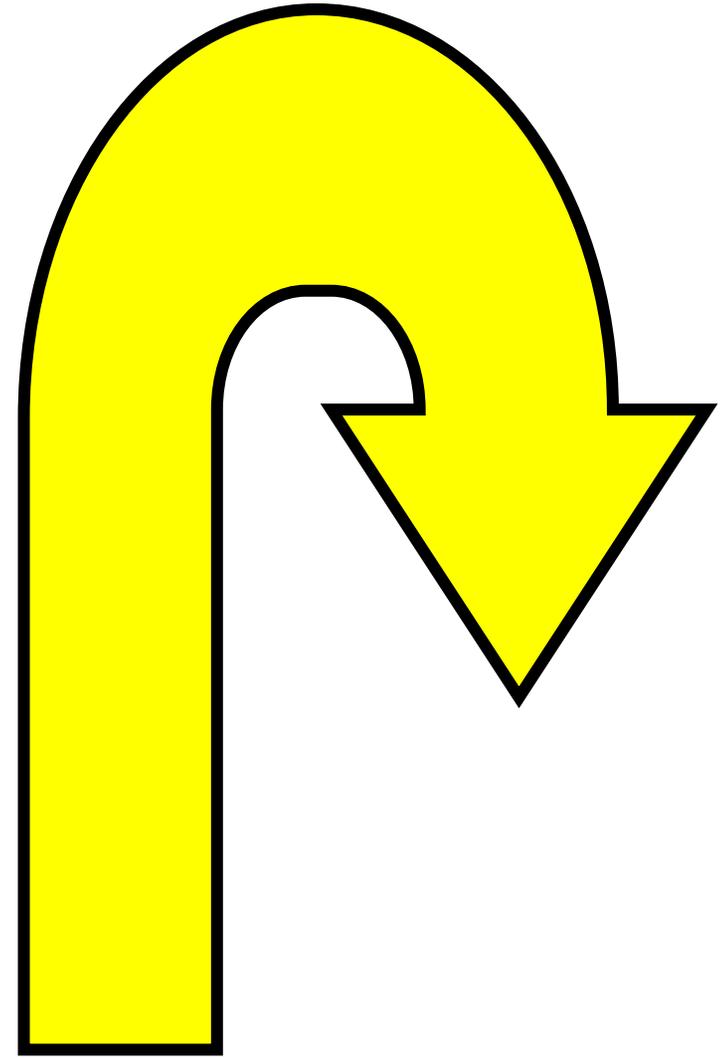
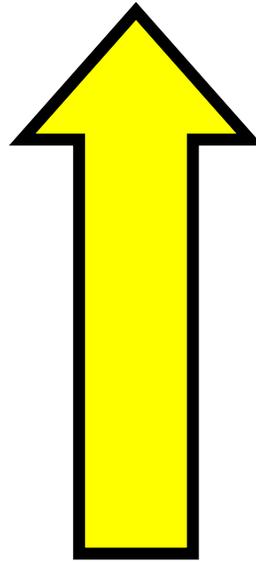
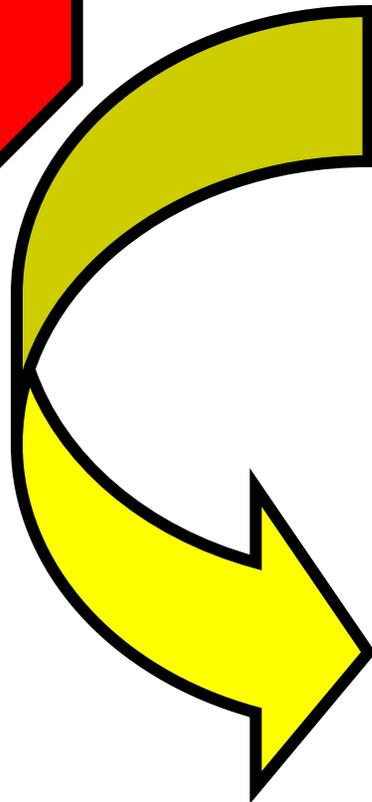
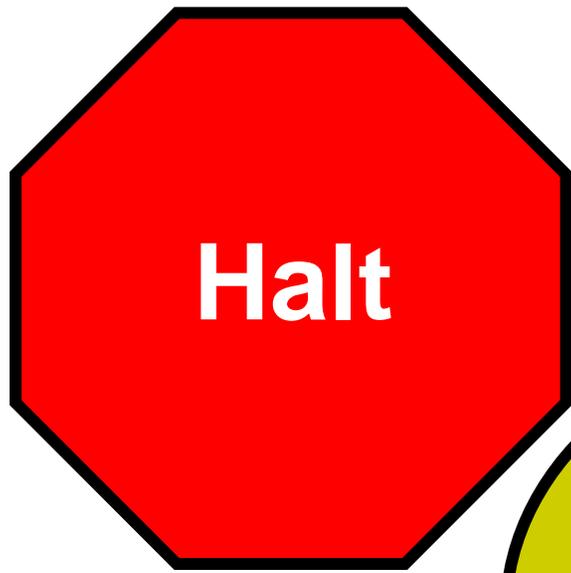


**Side Step
Right**

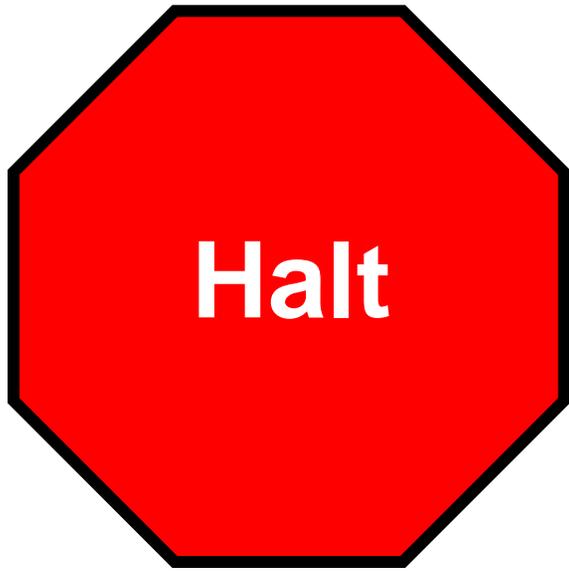




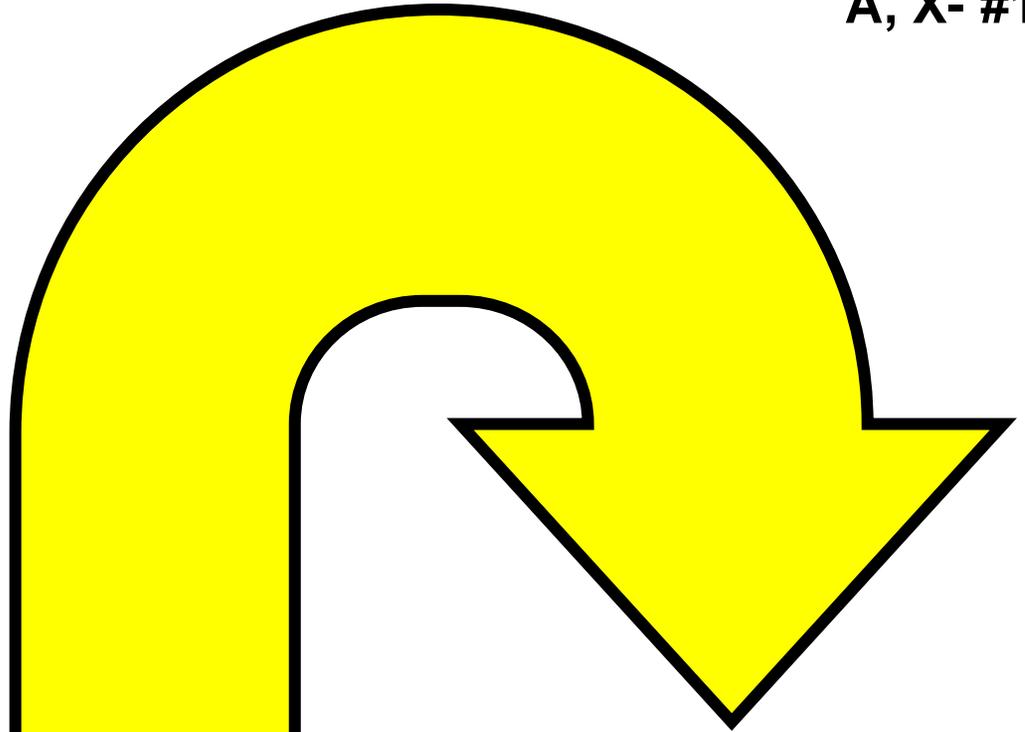
Call Dog
Front
Finish Right

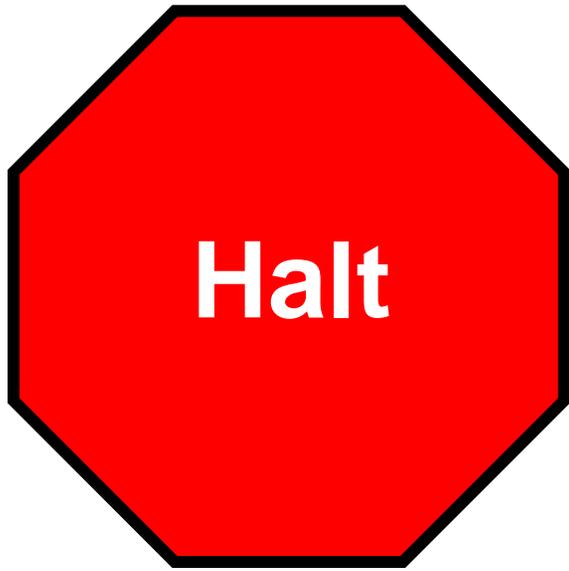


Call Dog Front
Finish Left

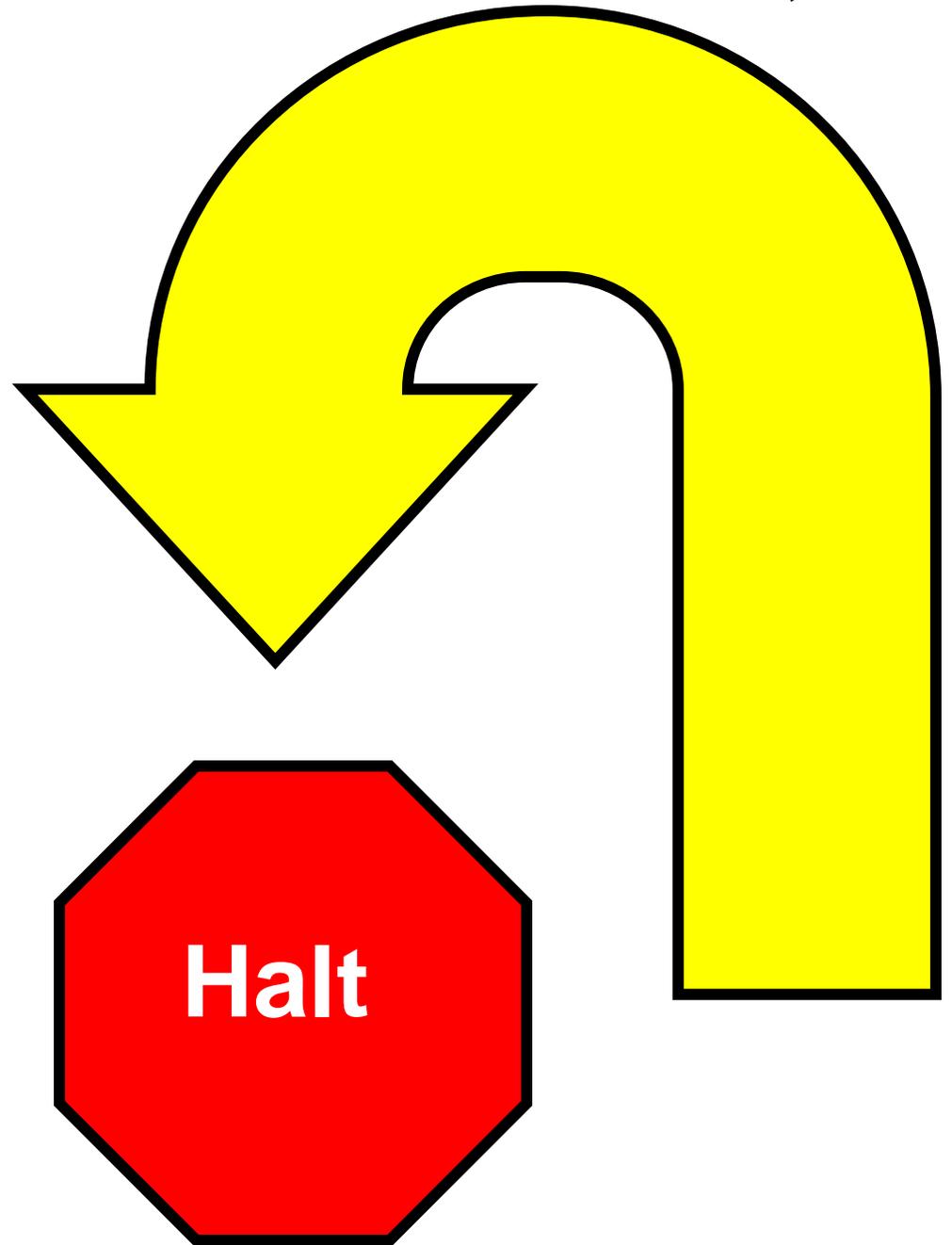


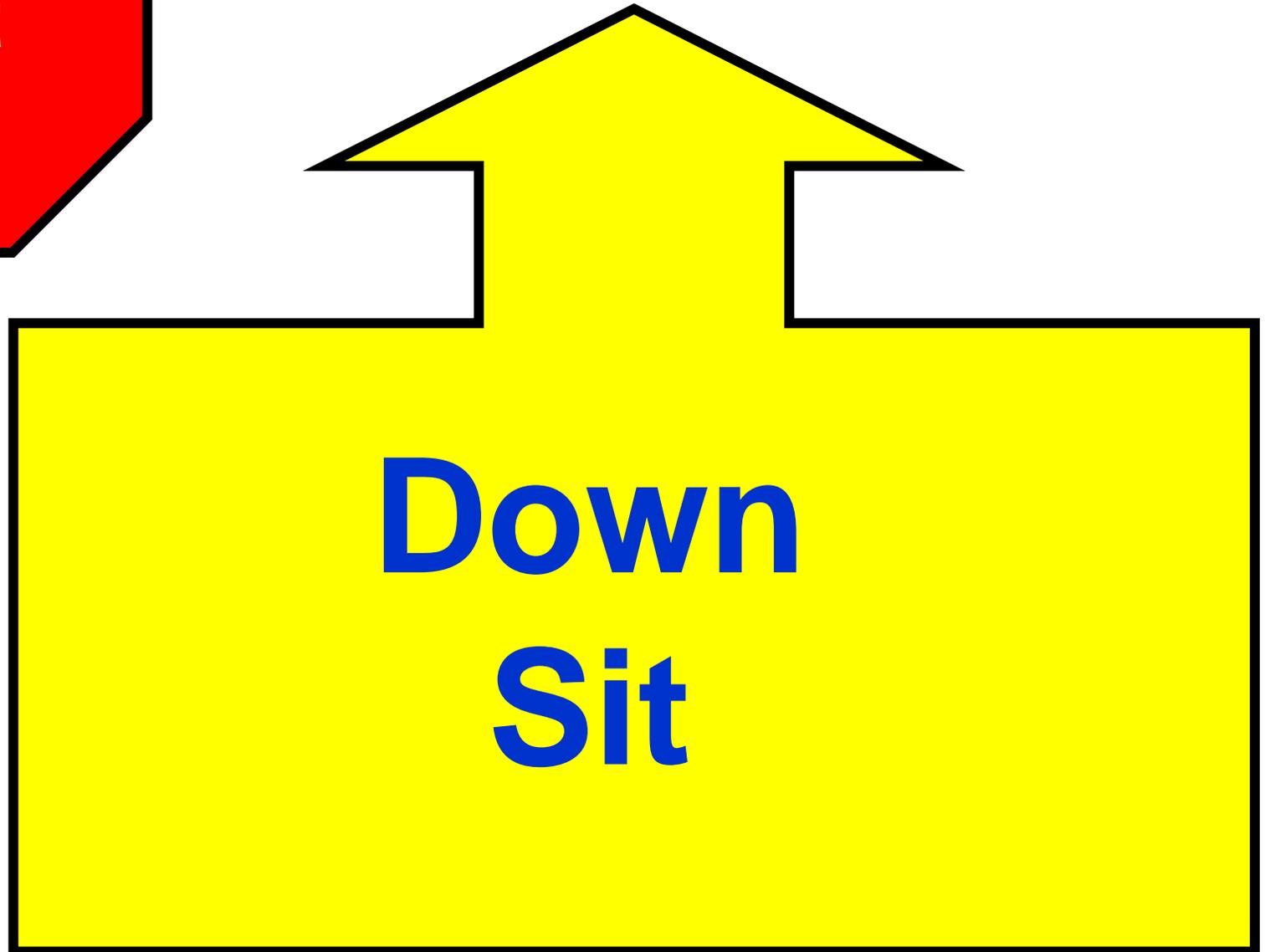
**180°
Pivot
Right**

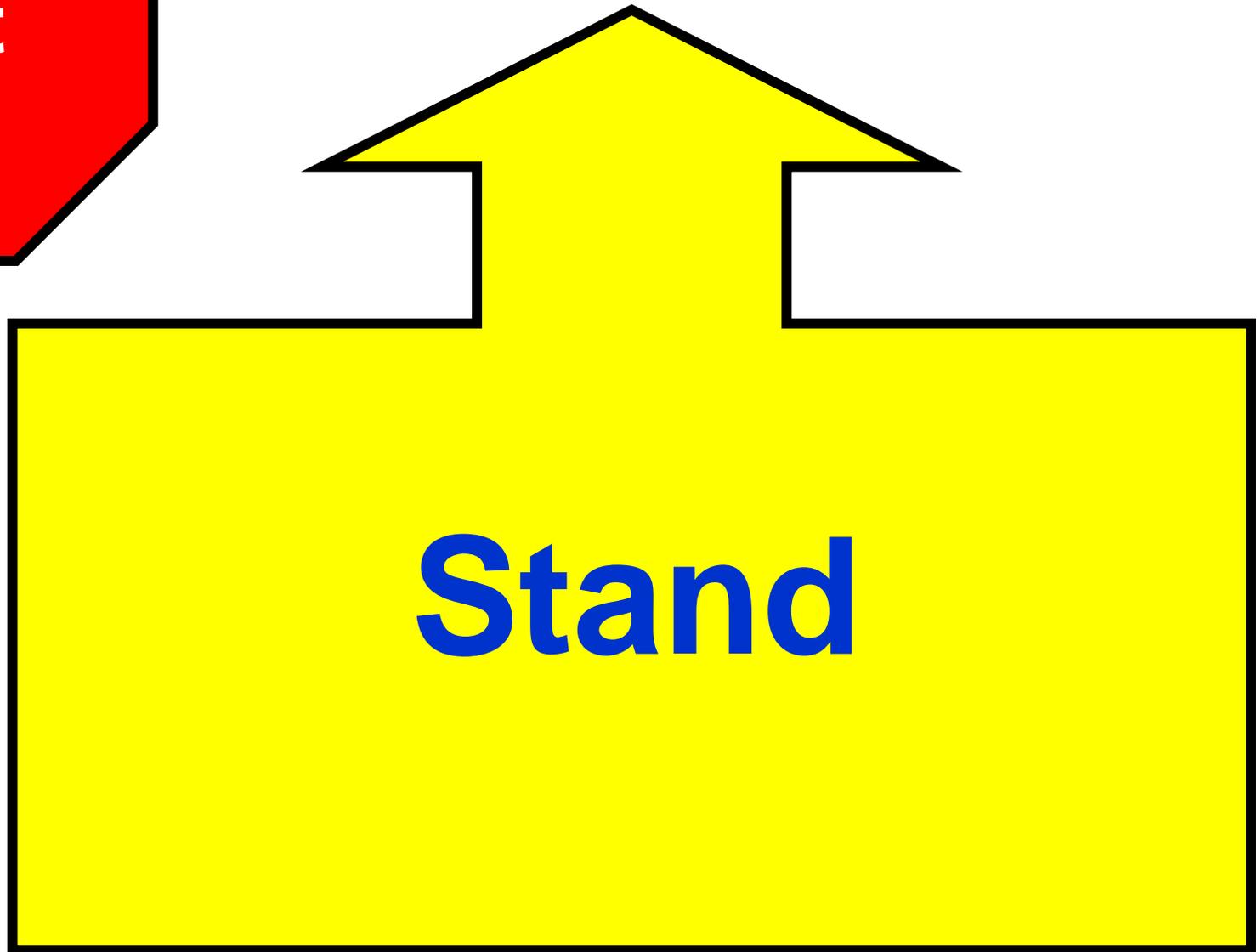
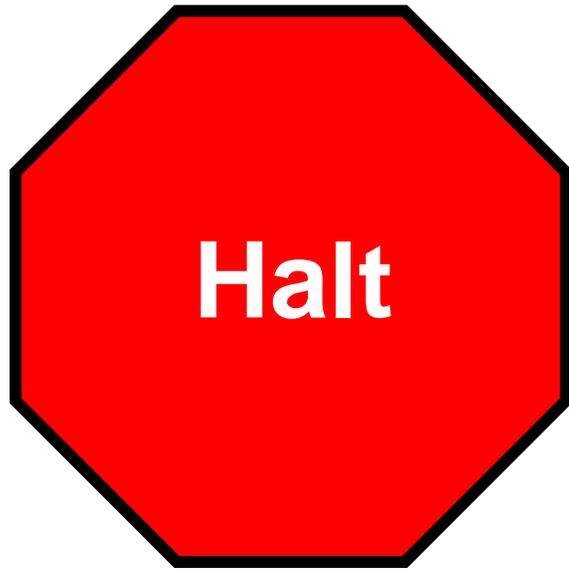


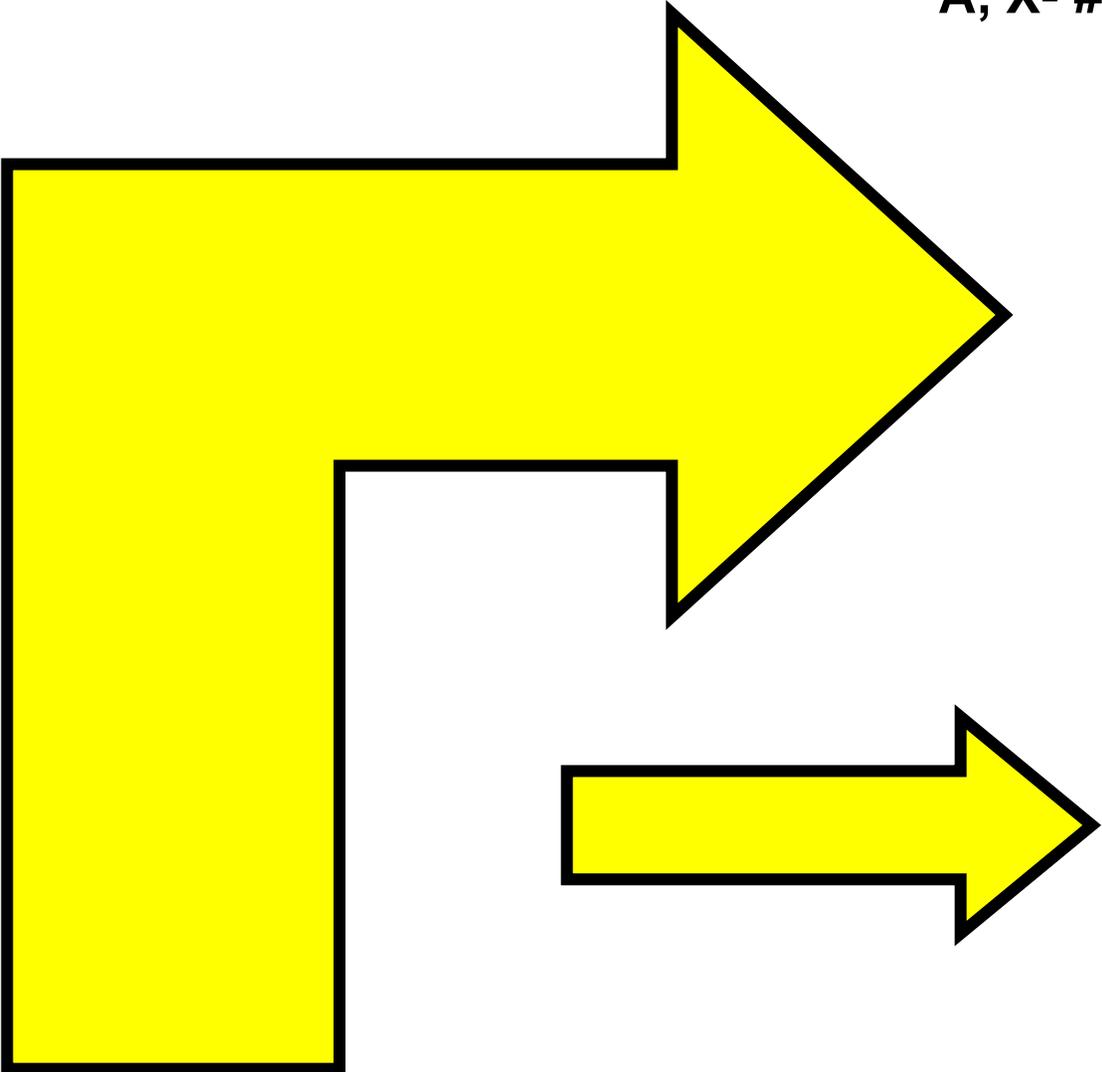


**180°
Pivot
Left**

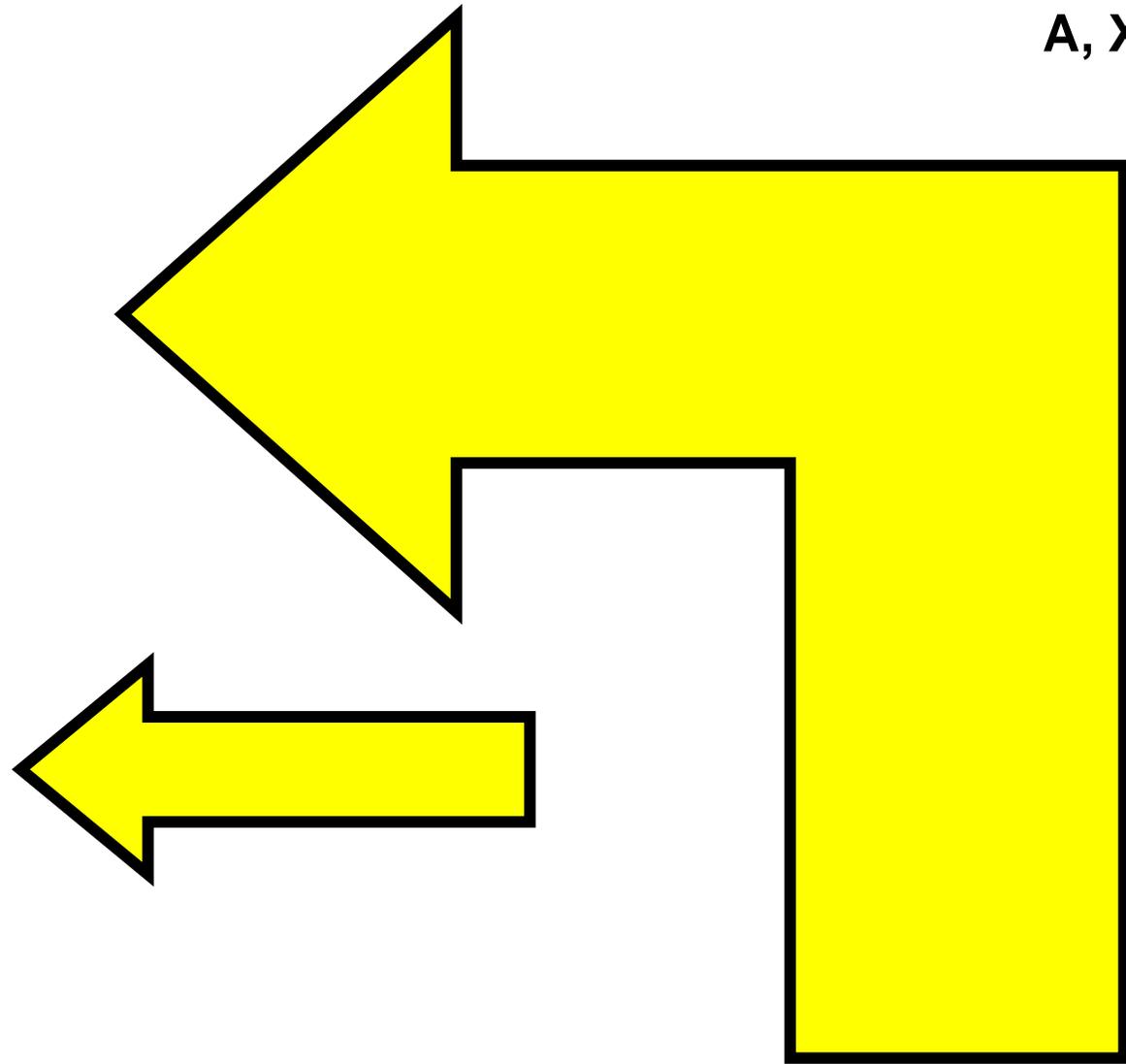
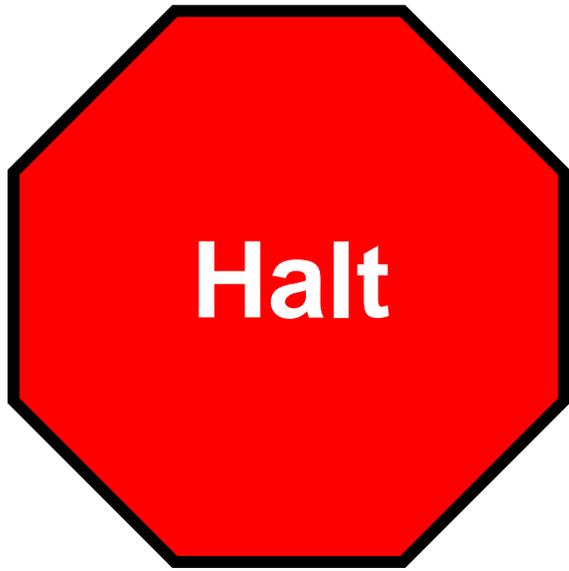






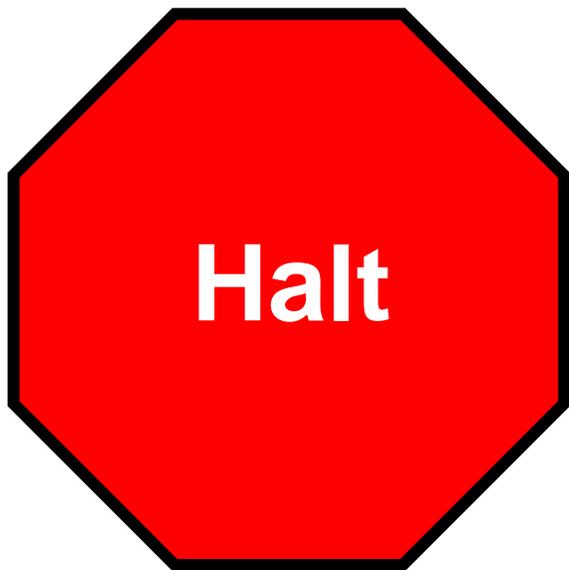


**Pivot
Right - Forward**



Pivot

Left - Forward

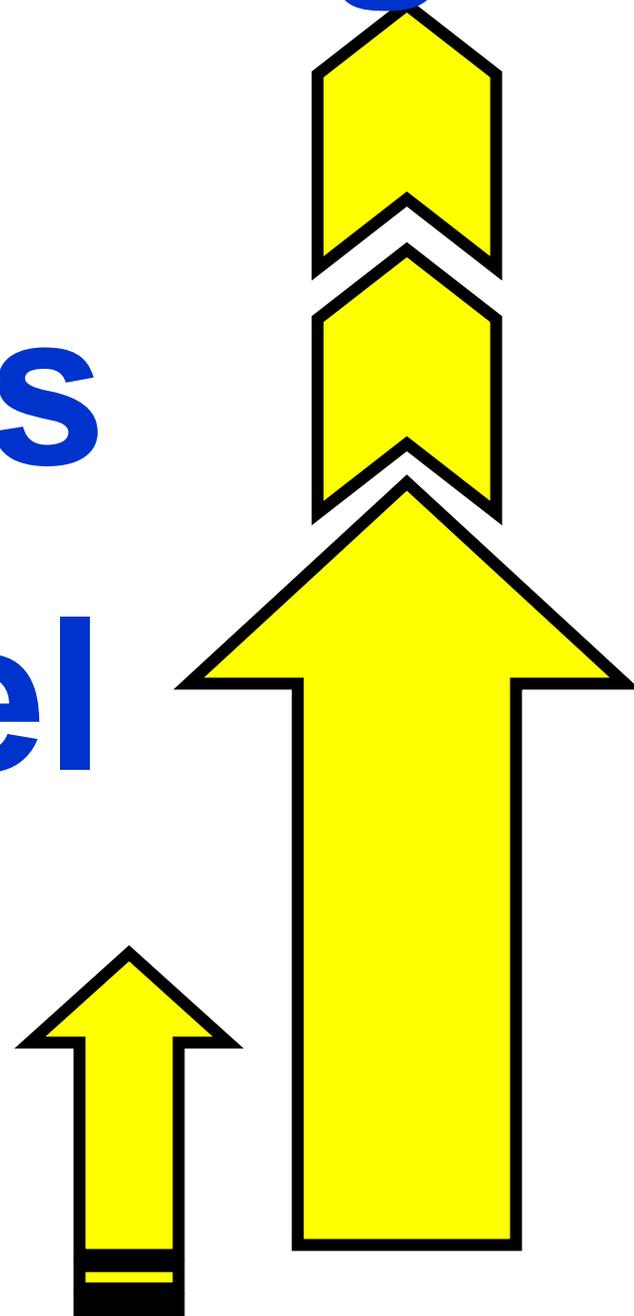


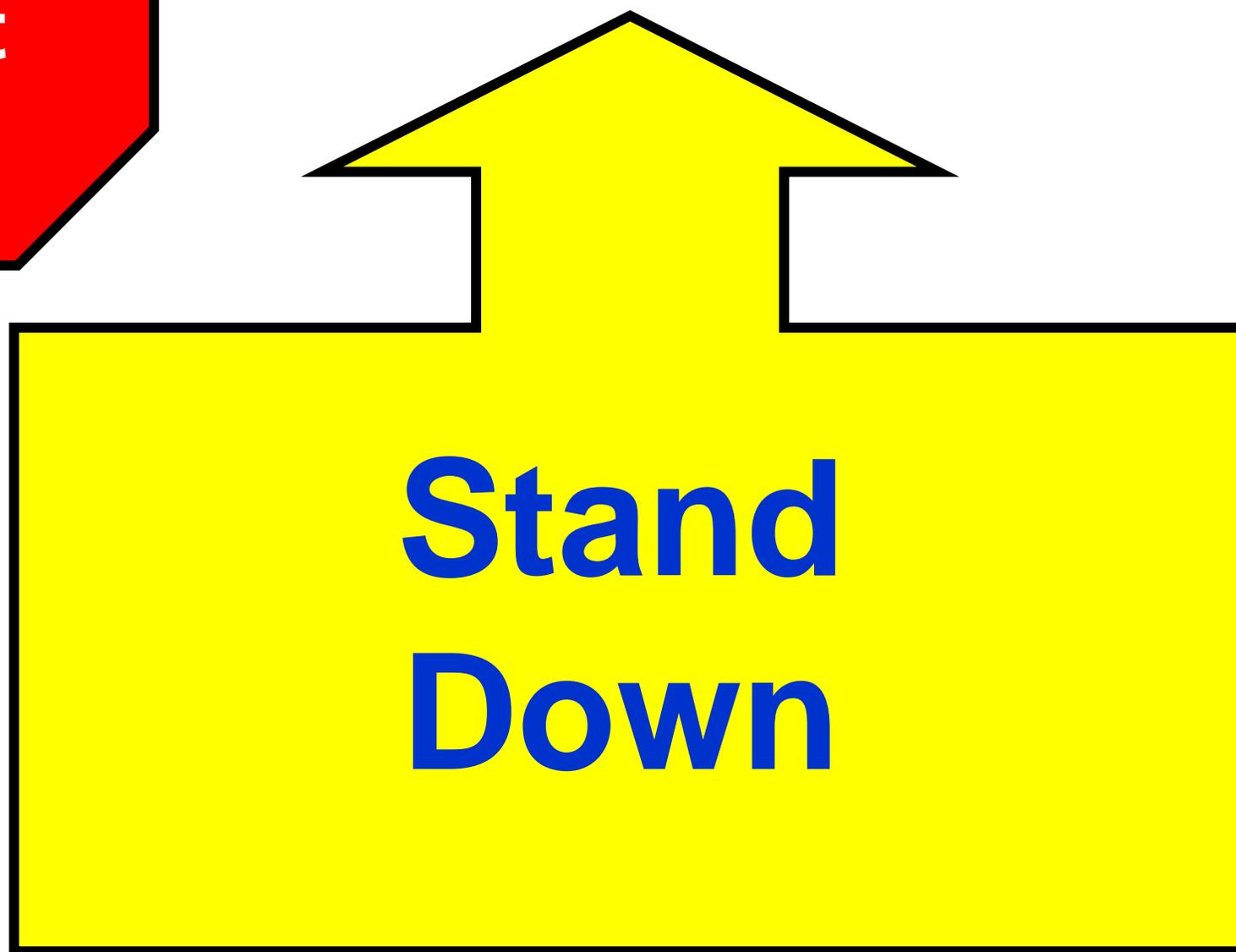
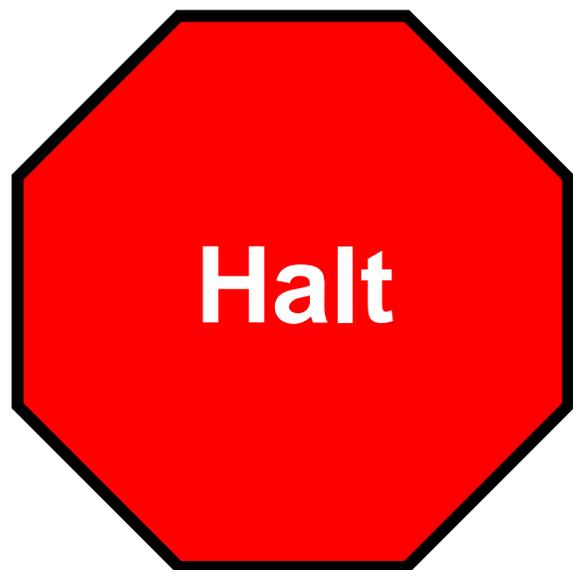
Leave Dog

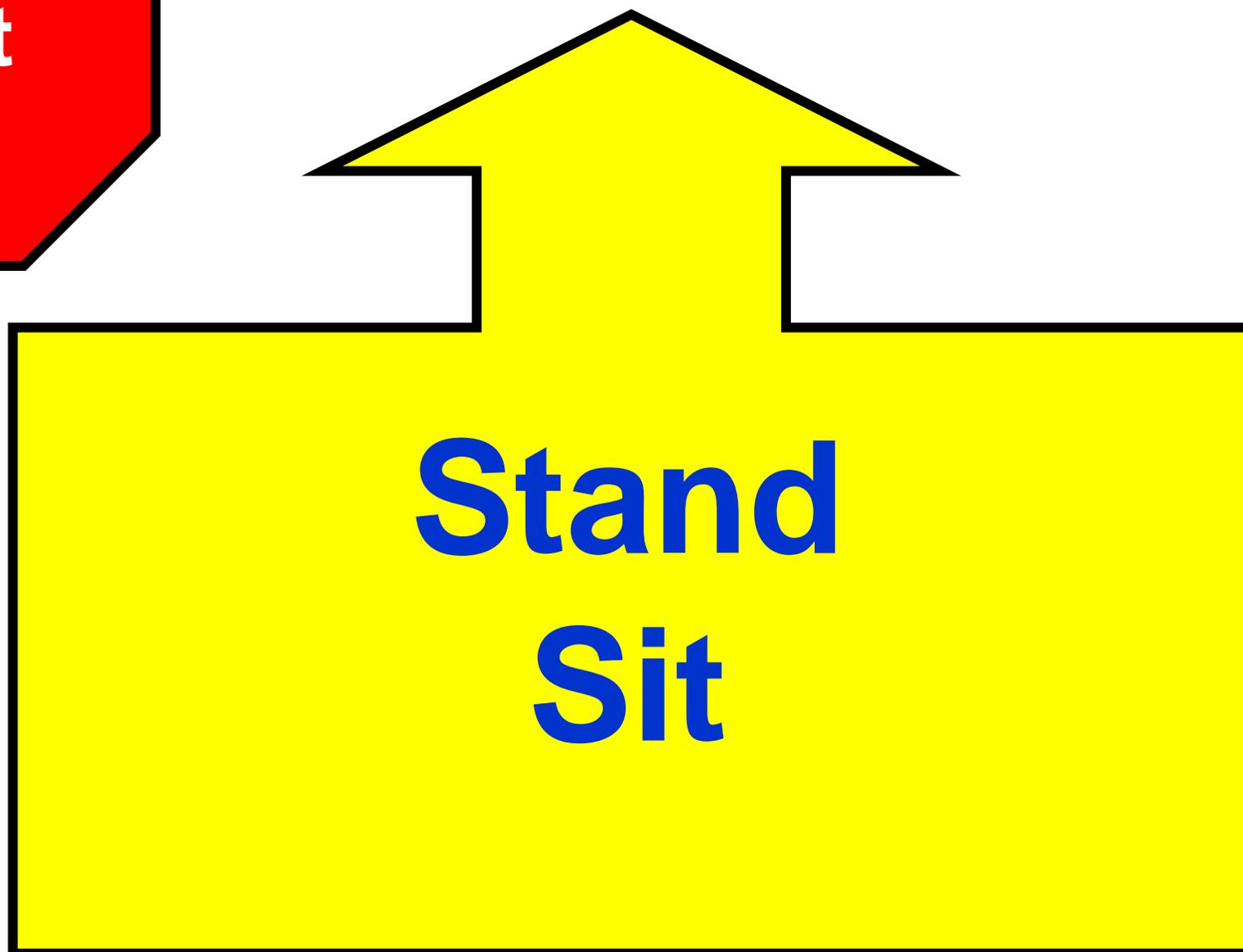
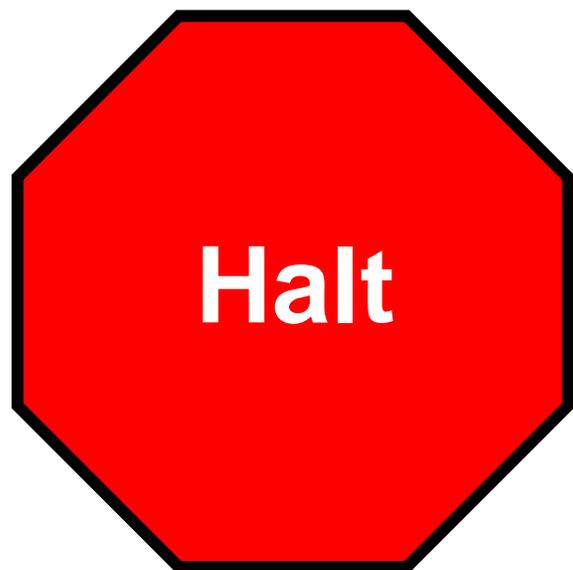
2 Steps

Call to Heel

Forward





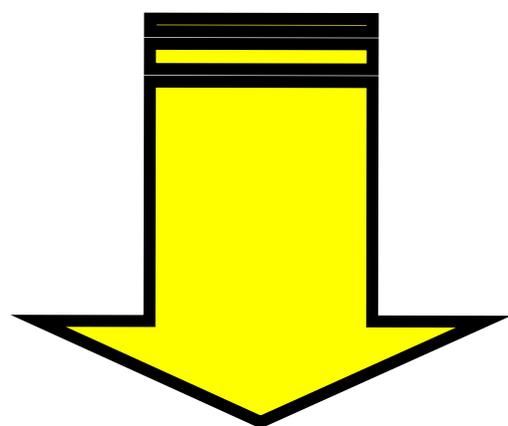
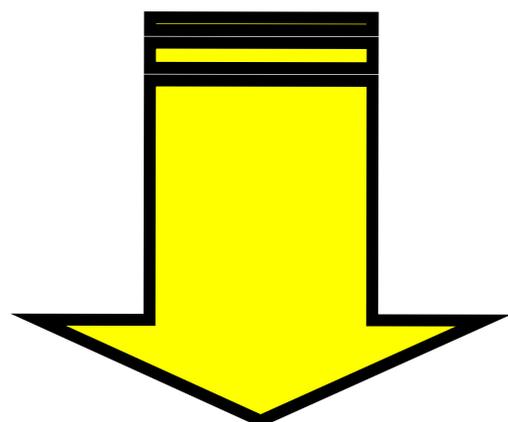
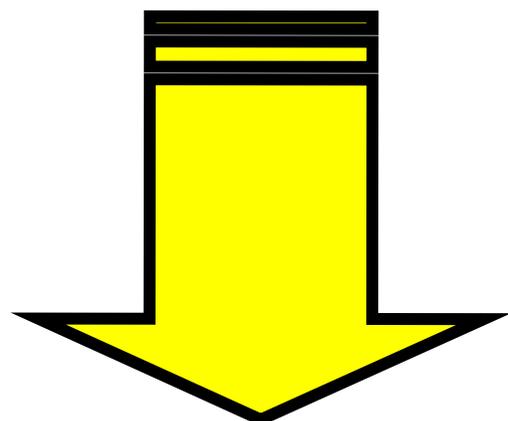




**Moving Stand
Walk Around
Dog**



**Moving Down
Walk Around
Dog**



**Back Up
3 Steps
Dog
Stays in
Position**



**Down
While Heeling**



**Stand
While Heeling**

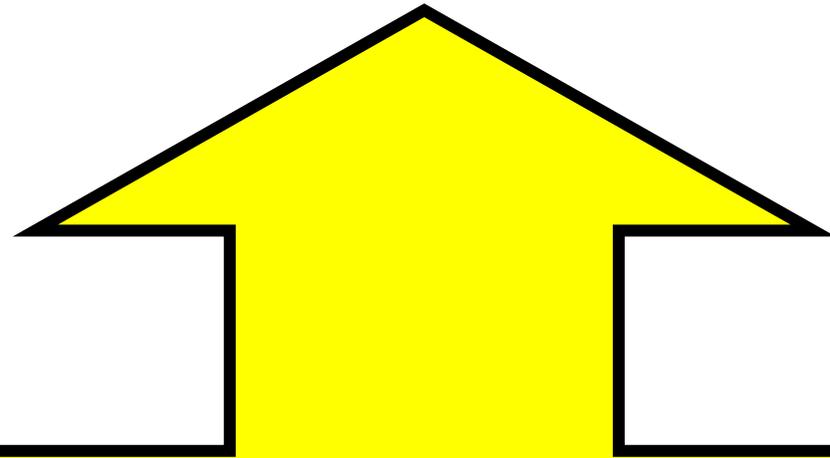


Stand

Leave Dog

Sit Dog

Call Front - Finish

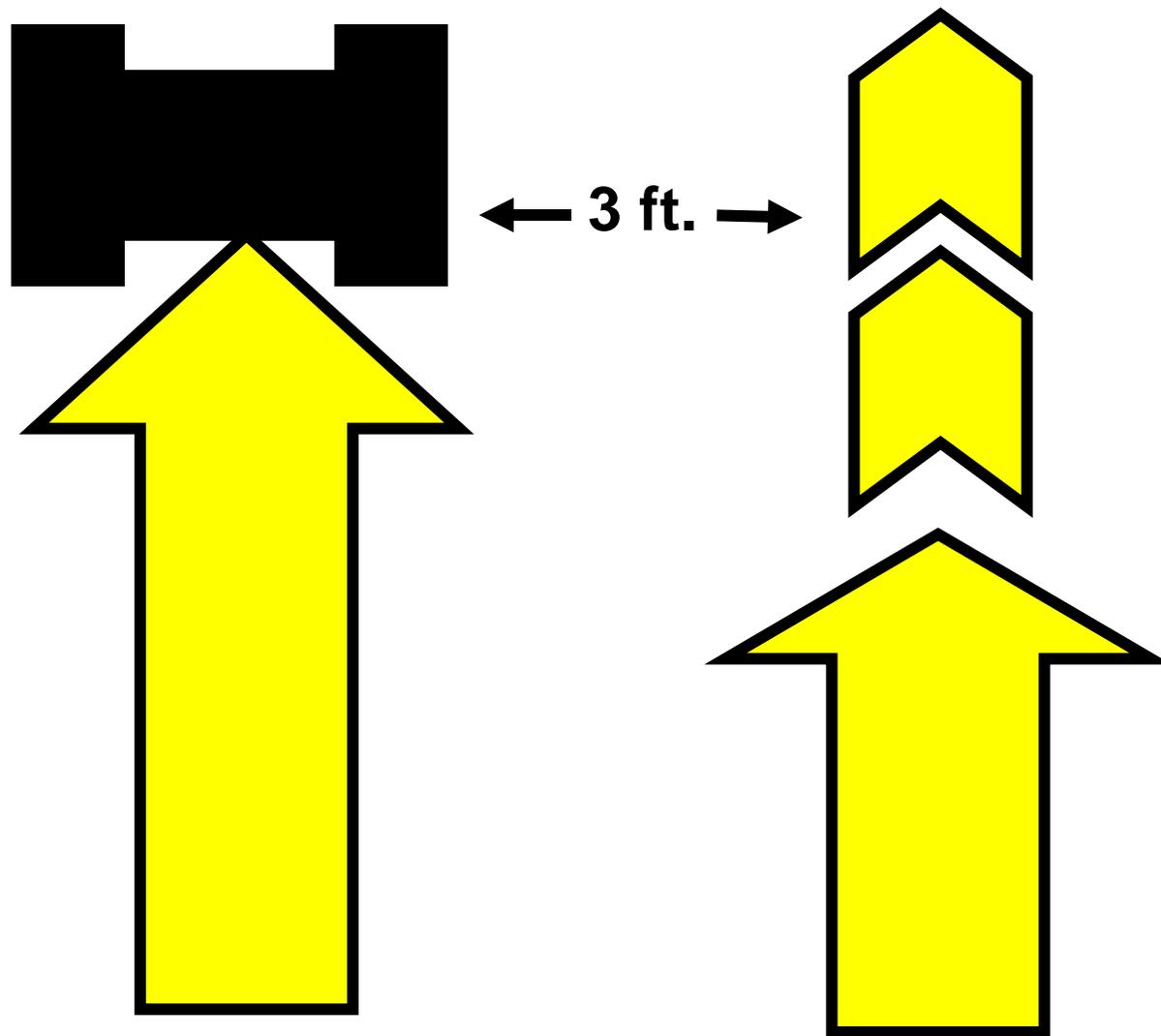


Stand

Leave Dog

Down Dog

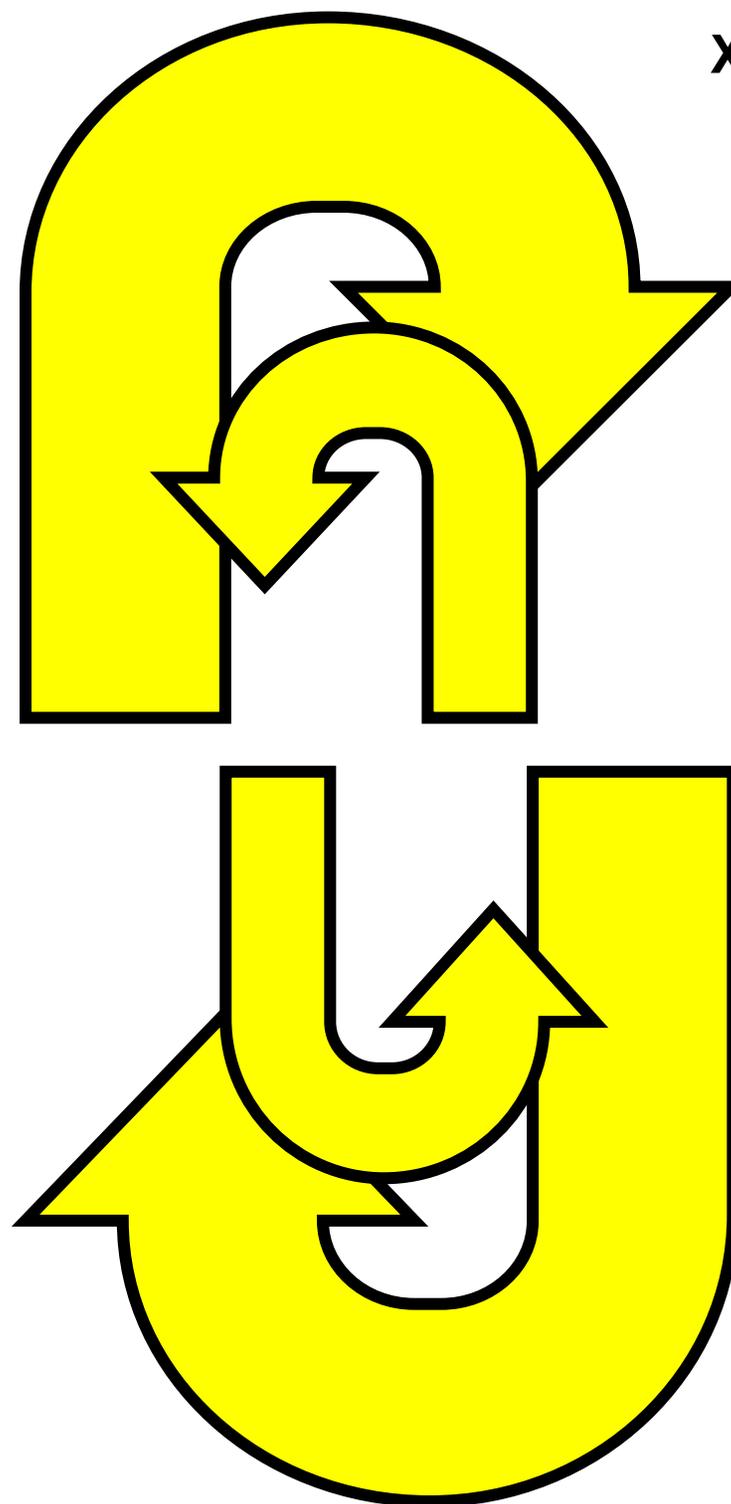
Call Front - Finish

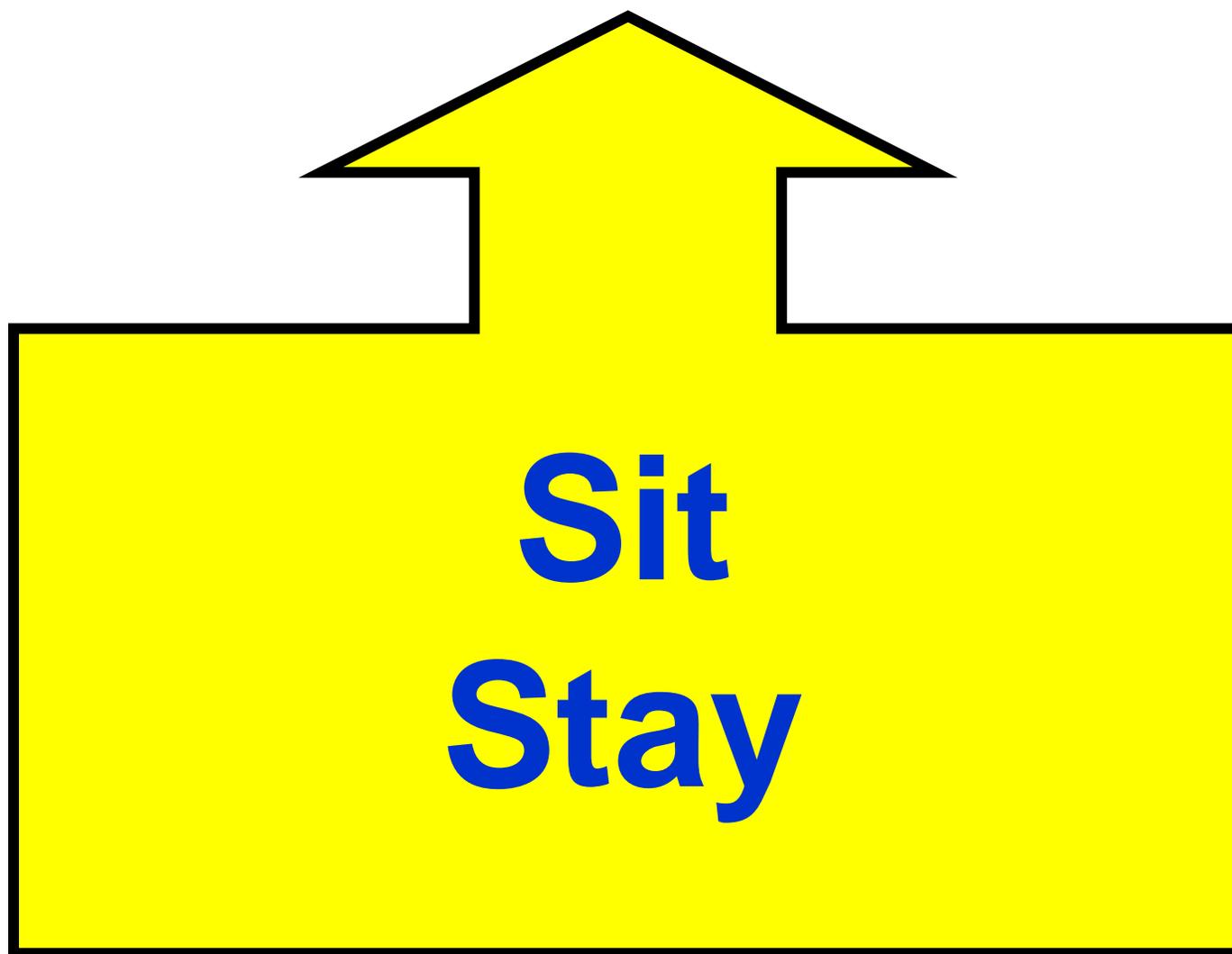


Send To Jump



**Double
Left
About
Turn**







X- #299

